1	The evolutionary relationship between beak shape, mechanical advantage,
2	and feeding ecology in modern birds
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32 ABSTRACT

33 Extensive research on avian adaptive radiations has led to a presumption that beak morphology predicts feeding ecology in birds. However, this ecomorphological 34 relationship has only been quantified in a handful of avian lineages, where associations 35 are of variable strength, and never at a broad macroevolutionary scale. Here, we used 36 shape analysis and phylogenetic comparative methods to quantify the relationships 37 between beak shape, mechanical advantage, and two measures of feeding ecology (feeding 38 behaviour and semi-quantitative dietary preferences) in a broad sample of modern birds, 39 comprising most living orders. We found a complex relationship, with most variables 40 41 showing a significant relationship with feeding ecology but little explanatory power, for example, diet accounts for less than 12% of beak shape variation. Similar beak shapes 42 are associated with disparate dietary regimes, even when accounting for diet-feeding 43 behaviour relationships and phylogeny. Very few lineages optimize for stronger bite 44 forces, with most birds exhibiting relatively fast, weak bites, even in large predatory taxa. 45 The extreme morphological and behavioural flexibility of the beak in birds suggests that, 46 far from being an exemplary feeding adaptation, avian beak diversification may have 47 been largely contingent on trade-offs and constraints. 48

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50 Keywords: birds, beak shape, feeding ecology, diet, mechanical advantage, adaptation

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1. Introduction

In birds, a strong link between the shape of the beak and dietary habits is assumed as a 56 truism (e.g.: Gill 1995), likely arising from the central role that the study of Darwin's finches 57 played in the conception (Darwin and Wallace 1858; Darwin 1859) and further development 58 of natural selection in evolutionary theory (e.g. Lack 1940; Hamilton and Rubinoff 1963; 59 Schluter and Grant 1984; Grant and Grant 1993, 2002, 2006; Lamichhaney et al. 2018). 60 61 However, feeding selective pressures do not necessarily produce a simple match between beak phenotype and ecology. For instance, pleiotropic interactions during development might 62 63 impose restrictions to trophic selection (Lieberman 2011), or 'specialized' beak phenotypes might be retained if they are efficient for processing non-favoured resources, particularly if the 64 favoured resource is periodically limited (i.e. Liem's paradox; Liem 1980; Tebbich et al. 2004). 65 Furthermore, in addition to feeding and foraging, birds use their beaks for a plethora of other 66 tasks, such as preening (Moyer et al. 2002; Clayton et al. 2005), vocal modulation (Podos 2001; 67 Herrel et al. 2009), thermoregulation (Tattersall et al. 2009; van De Ven et al. 2016) and water 68 balance (Greenberg et al. 2012), tool use (Weir et al. 2002; Wimpenny et al. 2009; Laumer et 69 al. 2017), nest construction (Hansell 2000), and as a display structure (Navarro et al. 2009). 70 This functional and behavioural flexibility implies that multiple selective pressures likely 71 played important roles in shaping beak evolution. Understanding the relative importance of 72 trophic adaptation to beak morphological diversification in modern birds is therefore vital to 73 74 understanding avian evolution, and to make accurate ecological inferences in extinct taxa (Lauder and Thomason 1995; Rubega 2000). 75

Although the main patterns of beak shape evolution at a broad macroevolutionary scale in birds have been effectively characterized (Cooney et al. 2017), the extent to which such patterns are related to feeding ecology, or to biomechanically relevant traits such as the mechanical advantage of the jaws, remains largely unexplored. Besides Darwin's ground

finches (e.g. Grant and Grant 2006), quantitative evidence evaluating the link between feeding 80 ecology and beak shape in birds is limited to a handful of avian clades (Rubega 2000). These 81 few studies have found strong associations in several families of passerines (Gosler 1987; 82 Benkman 1988; Price 1991; Peterson 1993; Bardwell et al. 2001), anseriforms (Olsen 2017), 83 and a few charadriforms (Barbosa and Moreno 1999), but weak associations among birds of 84 prey (Bright et al. 2016). Biomechanical modelling is similarly limited taxonomically, but in 85 86 Darwin's finches, it has been shown that skull and beak shapes are adapted to the mechanical demands of feeding (Soons et al. 2010; Soons et al. 2015). 87

88 Here, we use geometric morphometrics (GM) to quantify beak shape variation and its relationship with feeding ecology in a broad sample of birds. Shape analysis based on GM 89 provides the analytical tools to partition the sources of beak shape evolutionary variance, as 90 91 well as to test the strength and pattern of correlation with independent variables (Monteiro, 1999; Rohlf and Corti, 2000; Marugán-Lobón et al., 2013). Ecology is characterised by three 92 components of feeding: we quantify the mechanical advantage (MA) of the jaws as a functional 93 trait related to the ability to transfer force or movement through the skull system (high MA 94 describes efficient force transfer, low MA defines less efficient force transfer but faster jaw 95 movement (1); tabulate biological role by documenting use of the beak during feeding (2); and 96 recompile detailed semi-quantitative dietary data (3) for each of the studied species. We use 97 multivariate statistics and phylogenetic comparative methods to test for correlations between 98 99 these variables, while also accounting for the effect of size (i.e. evolutionary allometry) on beak shape, force transfer, and diet. 100

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102 **2. Material and methods**

103 **2.1. Database, trophic information, and phylogenetic hypothesis**

Our study includes 175 species from 94 families of extant birds, encompassing 38 of the 39 living orders, excluding only Mesitornithiformes, a Madagascan clade of three species (Hackett et al. 2008; Del Hoyo et al. 2017) (SM. Table 1). A maximum clade credibility phylogeny of the 175 species was generated using TreeAnnotator (Rambaut and Drummond 2013) from a population of 10,000 "Hackett's backbone 'stage 2' trees" downloaded from www.birdtree.org (Jetz et al. 2012) (Fig. 1). Branch lengths were set equal to 'Common ancestor' node heights.

The feeding autecology (the presumed main biological role of the beak) of each species 111 112 was characterized using two sources of ecological information, namely, semi-quantitative dietary preferences, and the use of the beak during feeding (UBF) (Fig. 1). The dietary data for 113 each species were sourced from EltonTraits 1.0 (Wilman et al. 2014). This data was coded as 114 a matrix of estimations of the relative importance of ten main dietary categories translated from 115 species-level dietary descriptions in the literature (Fig. 1, SM. Table 1) to the overall diet of 116 each species. These estimations were coded as bins of 10 units of percentage (i.e. 0, 10, 20, 117 30...100%) (Fig.1, SM. Table 1). A detailed description of the specific food items included in 118 each category is included in the metadata archives in Wilman et al. (2014). To obtain a 119 Euclidean representation of this non-continuous data we calculated a symmetric 120 similarity/distance matrix (Euclidean distances) from the original 175 (species) x 10 (dietary 121 items) matrix to conduct Principal Coordinates Analysis (PCoA) in PAST v.3.15 (Hammer et 122 123 al. 2009) and used the scores from the PCoA for downstream analyses (following Legendre and Anderson 1999). 124

The use of the beak during feeding (UBF), was categorised by applying a simple dichotomous key (SM. Fig. 1) to published observations of foraging and feeding behaviour of each of the studied species (Del Hoyo et al. 2017). This allowed us an alternative means to subdivide feeding autecology given that dietary categories at such a wide phylogenetic scale

often include very different foraging and feeding behaviours. For instance, the Atlantic puffin 129 (Fratercula arctica) and the osprey (Pandion haliaetus) both feed almost entirely on fish 130 (Wilman et al. 2014; Del Hoyo et al. 2017), but while the former feeds by underwater pursuit-131 diving and grabs individual fish directly with the beak, the latter plucks fish from the water 132 with the talons, and uses the beak instead to tear off chunks of meat before consumption (Del 133 Hoyo et al. 2017). The UBF categories for these examples are therefore scored as 134 135 'Grabbing/gleaning' and 'Tearing' respectively (SM. Table 1). Every species in our dataset except the American flamingo (Phoenicopterus ruber, a specialized filter feeder) fits in to one 136 137 of five categories (tearing, cracking/biting, pecking/grazing, grabbing/gleaning, and probing; Fig. 1; SM. Fig. 1). 138

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140 **2.2. Beak shape and size**

The skull of each species (without the rhamphotheca, the corneal sheath that covers the 141 bony beak, which is commonly missing in museum specimens) was photographed in lateral 142 view (SM. Table 1), and the complete outline of the beak was digitized using a set of 3 fixed 143 landmarks and 2 curves (Fig. 2), the latter comprising 50 evenly-spaced semilandmarks (25 144 along the dorsal profile of the bill (culmen), and 25 the left dorsoventral edge of the beak 145 (tomium)). The landmarks and semilandmarks were digitized in tpsDig2 (Rohlf 2006). The 146 Minimum Bending Energy sliding method (Bookstein 1996, Bookstein 1997) was used to slide 147 the semilandmarks in tpsRelw (Rohlf 2010), as this is more reliable when morphological 148 variation is large (Perez et al. 2006; Fernández-Montraveta and Marugán-Lobón 2017). Shape 149 data (i.e. Procrustes coordinates) was extracted using a full Procrustes fit and imported to 150 MorphoJ (Klingenberg 2008), PAST v.3.15 (Hammer et al. 2009) and the R package geomorph 151 v. 3.0.6 (Adams et al. 2018), where all the subsequent analyses were performed. Preliminary 152 analyses revealed that slender, straight beaks are consistently associated with higher values of 153

log-centroid size (CS; SM. Figure 3, SM. Table 5). This is undesirable as it may erroneously
exaggerate allometric effects particularly when, variance is very skewed towards one direction,
impeding our ability to reliably test for allometry using centroid size (Bookstein, 1991). Beak
allometry was therefore assessed using species-average body mass data (BM) taken from
Wilman et al. (2014).

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160 **2.3. Biting mechanical advantage**

Mechanical Advantage (MA) is a metric derived from lever mechanics (e.g. Uicker et 161 162 al. 2011) and a well-established functional trait describing the trade-off between bite force transmission and jaw closing speed during biting in vertebrates (e.g., Westneat, 1994; 163 Anderson et al. 2008; Sakamoto 2010). Given the same force input, a high MA indicates a 164 relatively more forceful bite; low MA indicates a relatively less forceful but faster bite. MA is 165 calculated as the ratio of the length of the in-lever divided by the length of the out-lever (Uicker 166 et al. 2011) and was determined for each species' skull at two different bite points (Fig. 2). The 167 in-lever arm here is defined as the orthogonal distance from the mandibular articular facet of 168 the quadrate (the fulcrum) to the intersection point with the midline of the fossa temporalis 169 between the postorbital and zygomatic processes of the skull, where the midline of the adductor 170 mandibulae group lies, which is the main adductor muscle group in modern birds (i.e. m. 171 adductor mandibulae externus medialis/superficialis (m. AMEM/S), Sustaita 2008; 172 Lautenschlager et al. 2014)(Fig. 2). 173

The out-lever arms are defined as the linear distance from the articular facet of the quadrate to the tip of the bony beak (i.e. landmark 1; anterior out-lever) or to the midpoint on the tomial curve bisecting landmarks 1 and 3 (posterior out-lever; Fig. 2). This approximates the mechanics of avian jaw closure as a 2D, third-class lever system, although the threedimensional lever system is often more complex than this (Olsen and Westneat 2016). Lever arm measurements were taken for each species using ImageJ (Rasband 1997). As anterior and
posterior MA values (as defined here) show a strong correlation (SM. Fig. 2), for simplicity
we only used anterior MA for all the subsequent analyses.

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2.4. Statistics

A Principal Component Analysis (PCA) on the Procrustes shape data was performed in 184 185 MorphoJ to explore the main patterns of beak shape variation. We mapped the phylogeny onto the PC scores in MorphoJ using the weighted squared-change parsimony method (Maddison 186 187 1991) to visualize changes in beak shape along the phylogeny (i.e., in the terminals and internal nodes). The phylogeny was also mapped over the anterior MA values to visually explore the 188 changes in MA in MorphoJ using the weighted squared-change parsimony method. Anterior 189 190 MA values were also mapped as isoclines over the PC1-3 phylomorphospace plots using the software MATLAB (Grant et al. 2008). 191

We used phylogenetically informed (Phylogenetic Generalized Least Squares, PGLS) 192 regressions to test for potential correlations between our trophic data, MA, size, and beak shape 193 variation using the R package geomorph v. 3.0.6 (Adams et al. 2018). Specifically, we tested 194 six pairwise relationships (Fig. 2): 1) beak shape variation and log-BM, to test if beak shape 195 variation is allometric; 2) MA and log-BM, to test if MA variation is allometric; 3) the 196 relationship between beak shape and MA; 4) the relationship between beak shape and dietary 197 198 preferences; 5) the relationship between MA and dietary preferences; and 6) the relationship between BM and dietary preferences. PGLS regressions with dietary preferences as the 199 independent variables also included UBF categories as a factor to account for the complex 200 relationship between the dependent variables (i.e., beak shape, MA and log-BM), dietary 201 preferences (i.e., matrix of diet), and feeding behaviour (i.e., UBF categories). 202

Phylogenetic MANOVAs were conducted in the R package geomorph v. 3.0.6 to test for 203 pairwise differences in: 1) beak shape; 2) MA; and 3) body mass between UBF group means. 204 205 Because our variables are unevenly dispersed across our phylogeny (e.g., specialized piscivorous taxa belong mostly within particular clades, Fig. 1), which can severely reduce 206 statistical power of linear models (Adams & Collyer, 2018), we used randomizing residuals in 207 a permutation procedure (10,000 iterations implemented in geomorph v.3.0.6, Adams et al. 208 209 2018) to assess statistical significance for all PGLS regressions and Phylogenetic MANOVAs, as this has been shown to be more robust to group-clade aggregations (Adams and Collyer, 210 211 2018). Furthermore, because dietary preferences and UBF categories covary with each other $(R^2 = 0.05547, F = 1.9848, Z = 2.2061, P = 0.023; e.g., taxa who use the beak for tearing tend$ 212 to consume a higher percentage of vertebrates (e.g. raptors), Fig. 1) we used type II 213 (conditional) sums of squares to assess the statistical significance of those PGLS linear models 214 including both dietary preferences and UBF groups (Adams and Collyer, 2018). 215

Current implementations of PGLS regressions assume a Brownian Motion mode of evolution. 216 To test if our data meets this requirement, we compared the relative fit of the estimated 217 residuals of shape, MA, and body mass to three different models of evolution: Brownian 218 Motion, Ornstein–Uhlenbeck, and Early-Burst. We used the residuals of the PGLS linear 219 models conducted in this study and the AICc criterion to ascertain which model best fits the 220 data in each case (the one yielding the lowest AICc value). For shape data, fitting these models 221 222 requires reducing its dimensionality, therefore we used the first nine PCs (accounting for ~99% of the variancein all the PGLS models where shape is the independent variable). Brownian 223 Motion is only preferred over the other models in the PGLS model of mechanical advantage as 224 225 a function of diet. For the remaining PGLS models, the Ornstein–Uhlenbeck model is preferred, and only a small difference in AICc value in all the cases (except for the two PGLS 226 allometric models which are either non-significant, or significant but explain little shape 227

variance in our sample; Table 1; SM. Table 6). We therefore interpret that our data do not 228 greatly deviate from a Brownian Motion model of evolution, and thus meet the expectations of 229 the PGLS linear models. Nevertheless, these results must be taken cautiously, as recent 230 research suggests current model-fitting methods based on maximum likelihood are prone to 231 exhibit ill-conditioned covariance matrices that could lead to errors of interpretation (Adams 232 and Collyer, 2017). The implementation of more complex evolutionary models for analyses of 233 234 high dimensional data is not fully developed (Monteiro, 2013), therefore, it is a methodological endeavour that goes beyond the scope of this paper. 235

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Variation along shape vectors is displayed as thin-plate spline deformations of an outline diagram based on the lateral beak outline of the plush-crested jay (*Cyanocorax chrysops*, Corvidae, Passeriformes), the species which is most similar to the Procrustes mean. The coefficients from the PGLS regressions with shape as the dependent variable were used to calculate the beak shape differences along the regression vectors. The R code used for all the analyses is provided in the Supplementary Materials.

243

244 **3. Results**

245 **3.1. Beak shape, mechanical advantage, and allometry**

The first three principal components (PCs) explain 92.54% of the total shape variance in our sample, implying that few dimensions underlie beak shape variation. The main axes of beak shape recovered in this study (Fig. 3 & 4, and Supplementary Materials) are roughly equivalent to those recovered by a crowd-sourced study encompassing the 3D beak shapes of more than 2,000 species of modern birds (Cooney et al. 2017), suggesting that discarding the third dimension and rhamphotheca produces comparable patterns of avian beak disparity at this macroevolutionary level. Namely, our PC1 describes the same lateral shape change (thin and

straight, to deep and down-curved). Similarly, our PC2 (thin and curved, to deep and straight) 253 and PC3 (down-curved to slightly upturned) explain similar shape changes to Cooney et al.'s 254 PCs 2 and 4. While some groups of birds cluster within restricted areas associated with deeper 255 and curved beak shapes (e.g. Accipitriformes, Strigiformes, Falconiformes, and 256 Psittaciformes), several species or clades widely diverge from their sister groups to different 257 areas of the PC-space (e.g. Semnornis, Piciformes; Podargus, Caprimulgiformes; 258 259 Phoenicopterus, Phoenicopteriformes; the family Anatidae) or to cluster within the deep and curved scatter (e.g. Carduelis, Passeriformes; Musophaga, Cuculiformes; Figs. 3 & 4). PGLS 260 261 regression of beak shape on log-BM is not significant (P = 0.362) (Table 1, SM. Figure 5) revealing that beak shape allometry across birds as a whole is negligible. 262

Mechanical advantage varies from low force/high speed transmission values of 0.02 263 (anterior MA) to 0.035 (posterior MA) in the Eurasian curlew (Numenius arquata), to more 264 forceful values of 0.44 (anterior MA) - 0.55 (posterior MA) in the Finch's pygmy parrot 265 (Micropsitta finschii; Figs. 3 & 5, and SM. Table 1). However, MA values are generally low, 266 and 80% of the taxa possess anterior MA values < 0.14 (Figs. 3B & 5 and SM. Table 1). Plotting 267 MA over the PC1-3 space (Fig. 3A) reveals a broad trend between shape and MA: low MA 268 values in positive PC1 (thinner, straighter beaks) and higher MA values in negative PC1 269 (deeper, more curved beaks). However, the trend is not linear, and there are islands of high 270 MA, meaning that two taxa separated by small Procrustes distances may have quite different 271 272 MA values. This biomechanical decoupling is particularly noticeable between tearing (i.e. mostly raptors) and cracking birds (i.e. mostly parrots). For instance, the boreal owl (Aegolius 273 *funereus*, Strigiformes) and the hyacinth macaw (Anodorhynchus hyacinthus, Psittaciformes) 274 show a Procrustes distance of only 0.073 between their beak shapes but they show extremely 275 different anterior MA values (Fig. 3). Anterior MA values show a significant but weak 276 $(R^2=0.03479, P=0.014)$ correlation with body mass (Table 1; SM. Fig. 5). 277

Although mechanical advantage data shows a statistically significant phylogenetic 278 structure (P < 0.0001), most internal nodes are constrained to a narrow range of relatively low 279 MA (Fig. 3B). Only two lineages clearly diverge from this: parrots (Psittaciformes), which 280 explore more than half of the upper range of MA values; and sandpipers, snipes, and phalaropes 281 (Scolopacidae), with extremely low MA values (Fig. 3B & SM. Table 1). Some pheasants (e.g. 282 Perdix) also exhibit high values of MA within the range of Psittaciformes, along with some 283 284 specialized cracking/biting passerines such as the Northern cardinal (*Cardinalis cardinalis*) (Figs. 3 & 5). Clustering near the Psittaciformes with lower values of MA are mainly 285 286 herbivorous taxa such as the snow goose (Chen caerulescens), the common linnet (Carduelis cannabina), the Western capercaillie (Tetrao urogallus), and the least seedsnipe (Thinocorus 287 rumicivorus), as well as the Andean condor (Vultur gryphus). The latter represents a clear 288 289 deviation from the general low MA values of Accipitriformes (Figs. 3 & 5), due to a ventral deflection of the beak tip that shortens the out-lever of New World vultures (Cathartidae) 290 relative to the Old World vultures (Accipitridae). 291

PGLS regression of beak shape on anterior MA values exhibits a significant ($R^2 = 0.133$, 292 P < 0.0001) correlation (Fig. 5). The shape differences described by this regression vector are 293 remarkably similar to those described by PC1: thin, straight, long beaks (positive PC1) show 294 the lowest values of MA, while deep, curved beaks (negative PC1) show the highest. Deviating 295 from this general trend with much lower values of MA than predicted by the regression is the 296 297 majority of the tearing group, composed of the Accipitriformes; the northern crested caracara (Caracara cheriway, Falconiformes); and Strigiformes (Figs.1 & 5), which do not comprise a 298 monophyletic assemblage (Hackett et al. 2008; Jarvis et al. 2014; Prum et al. 2015; Fig. 1). The 299 remaining Falconiformes cluster closer to parrots than to other raptors, exhibiting higher values 300 than the rest of raptors (Fig. 5). 301

302 3.2. Beak shape and feeding ecology

PGLS regression of beak shape as a function of dietary preferences and UBF revealed 303 a significant but weak correlation between beak shape and overall dietary habits ($R^2=0.1156$, 304 P=0.001; Table 2). The effect of UBF groups in beak shape variation is also statistically 305 significant but the correlation is not strong ($R^2=0.0923$, P=0.001) (Table 2). Such results are 306 largely congruent with visual inspection of the PC1-3 plot, where the main dietary groups 307 overlap without any clear separation, and UBF groups exhibit only slightly clearer 308 309 regionalization (Fig. 4). For instance, tearing and cracking/biting birds tend to occupy the same areas of the morphospace, being restricted to deep and curved shapes in the negative extreme 310 311 of PC1 (Fig. 4). Probing birds are restricted to the positive side of PC1, exhibiting relatively thin and straight shapes. Pecking/grazing taxa are restricted to approximately 0.0 - 0.1 on PC3, 312 exhibiting relatively straight and flat beaks (Fig. 4). However, Phylogenetic MANOVA shows 313 314 that none of the UBF group mean beak shapes are significantly different to any others (SM. Table 3) when phylogeny is accounted for. 315

Thin straight beaks tend to be associated with a higher percentage of invertebrate 316 consumption in birds, and deeper curved beaks are associated with consumption of more 317 mechanically demanding food items such as vertebrates and seeds (Fig. 6). Thin and slightly 318 curved beaks are also associated with highly piscivorous taxa (SM. Figs. 5 & 7), which together 319 with visual inspection of shape vectors associated with other axes of dietary variations 320 underlines that similar beak shapes are associated with disparate dietary regimes (SM. Figs. 5 321 322 & 7). Furthermore, regressions show that the relationship between beak shape and dietary preferences differs between UBF groups (Table 2; SM. Figs. 6 & 7), and that while there are 323 diet-dependent allometric relationships in our data, these are not affected by UBF behavioural 324 groups(SM. Table 4). 325

326 **3.3. Biting mechanical advantage and feeding ecology**

PGLS regression of anterior MA values as a function of dietary preferences and UBF 327 groups reveal a statistically significant correlation ($R^2=0.1692$, P=0.001; Table 2) that is 328 stronger than the relationship between beak shape and those measures of dietary ecology. 329 Higher values of MA are consistently associated with cracking/biting taxa, and those whose 330 diets rely heavily on plant matter, with large proportions of items such as fruits and drupes, 331 seeds, bulbs, shoots, grass or leaves (Fig. 6). Phylogenetic MANOVA revealed no pairwise 332 differences between any of the groups based on MA values (SM. Table 3). We found a strong 333 significant interaction between dietary preferences and UBF groups (R^2 =0.26376, P=0.001) 334 335 revealing that the relationship between diet and MA varies depending on the feeding behaviour (Table 2; SM. Fig. 6). 336

337 3.4. Body mass and feeding ecology

PGLS regression of log-body mass as a function of dietary preferences and UBF groups reveals a stronger correlation of body size with feeding ecology than that of both beak shape and MA with feeding ecology, with dietary variations explaining as much as 25% of log-body mass variation (Table 2). Visual inspection of the regression scores of log-body mass associated with the first axis of diet variation (PCo1) reveal that taxa with large amounts of invertebrates in their diet tend to be smaller, while some dietary groups such as scavengers tend to be associated with bigger sizes (Fig. 6).

UBF groups are only weakly associated with log-BM and none of the UBF groups are statistically different to any other in log-BM (SM. Table 2), although significant diet/UBF interactions reveal that different behavioural groups exhibit different body size to diet relationships (Table 2; SM. Fig. 6).

349

350 **4. Discussion**

Our analyses aimed to quantitatively test the common wisdom that feeding adaptation 351 is one of the main drivers of beak morphological diversification in modern birds. Our results 352 suggest that adaptation to dietary composition is not as fine-tuned as generally perceived, and 353 there is not a close to one-to-one mapping of beak shape on feeding ecology. At a broad 354 macroevolutionary scale, we found a more complex but weak overall covariation between beak 355 shape and diet, with other factors such as biting mechanical advantage and body size being 356 357 stronger covariates for feeding autecology. Similar beak shapes are associated with the increased consumption of different food items (i.e. a one-to-many relationship between shape 358 359 and ecology) and the relationship between beak shape and dietary preferences is different within different UBF groups, likely owing to the ecological heterogeneity of feeding behaviour 360 groups (i.e. many-to-one ecology to behaviour relationships). For instance, probing birds in our 361 sample are composed primarily of two very ecologically different groups: longirostrine waders 362 (e.g. Numenius, Gallinago, Limosa) and the kiwi (Apteryx), and anseriforms (e.g. Aythya, Anas, 363 *Cygnus*), which both use the beak during feeding as a probing tool in (mostly) soft substrates 364 (SM. Figs. 1 & 6). 365

Our results suggest that the beak is generally used as a versatile, tweezer-like clamp. 366 Mechanical pre-processing of food (i.e. tearing and cracking/biting feeding behaviours) is 367 generally associated with deep and curved beaks, which are able to accommodate 368 comparatively higher stresses than thinner, straighter beaks (Soons et al. 2010; Soons et al. 369 370 2015). Similarly, beaks well-suited for sensing and probing in fluid or soft soils tend to be long and thin (Barbosa and Moreno 1999). While such shapes represent the ends of a clear 371 ecomorphological spectrum it is difficult to predict where a given species should fall upon it, 372 373 as species well-suited for performing a certain feeding behaviour may not actually use their beaks in the way we would expect given their morphology (e.g. the kakapo, Strigops, has a 374 typically parrot-like beak well suited for cracking/biting, yet chooses to feed on soft leafy 375

vegetation rather than fruits or seeds). Most of the species studied fell between these extremes
in ecomorphology, using the beak for grabbing/gleaning or pecking/grazing, and exhibiting a
broad range of beak morphologies therein (i.e. many-to-one mapping of shape and behaviour).
Furthermore, the majority of bird taxa show values of anterior MA congruent with fast gapes
and low bite force transmission, and many of these belong to the grabbing/gleaning behavioural
group, which occupies virtually all of beak shape and functional space

382 We found a significant relationship between beak shape and mechanical advantage: increased values of anterior MA are strongly correlated with increased beak depth/length ratio, 383 384 driven, in part, by shortening of the beak, and suggesting that enhanced biting force transmission requires a deeper beak to accommodate higher stresses and avoid fracture (Soons 385 et al. 2010; Soons et al. 2015). However, this relationship differs between taxa, and thus 386 indicates a many-to-one relationship between shape and this functional trait. Raptorial birds 387 are interesting, as they have much lower anterior MA values than predicted by the general 388 regression. Initially this may be surprising, given the predatory nature of raptors, yet this result 389 is congruent with previous research showing that Strigiformes and Accipitriformes rely heavily 390 on talon adaptations to kill their prey (Sustaita 2008; Sustaita and Hertel 2010; Del Hoyo et al. 391 2017; Madan et al. 2017). Deep beak morphologies are, however, associated with enhanced 392 biting MA in the two taxa representing falconin falconiformes (Falconinae, Falconidae; Falco 393 and Herpetotheres). Falcons dispatch prey with their beaks rather than their talons (Sustaita 394 395 2008; Sustaita and Hertel 2010; Del Hoyo et al. 2017), which may explain why both falconid taxa differ from the other raptors and instead follow the general regression trend for all avians. 396 The evolution of faster gapes and comparatively weaker bite force advantage happen 397

primarily within the Charadriiformes (i.e. Scolopacidae). Unique modes of cranial kinesis, such
as distal and double rhynchokinesis (i.e., avian cranial kinesis characterized by additional
bending areas in the tip of the beak, and in both the tip and the base of the beak, respectively

(Zusi 1993; Estrella et al. 2007)), appear in this clade of mainly probing taxa, and could further 401 enhance gape speed. In contrast, comparatively slower gapes and enhanced biting force 402 transmission evolve less frequently. Parrots (Psittaciformes) are the most notable and extreme 403 example, especially when we consider that their mechanical advantage values here may be 404 underestimated, thanks to novel adductor muscles and skeletal adaptations which may enhance 405 lever efficiency in some parrots (Zusi 1993; Tokita et al. 2007). Our results suggest that dietary 406 407 transitions towards increased herbivory are correlated with evolutionary changes towards higher anterior MA, implying that herbivory imposes higher performance demands on the beak. 408 409 This observation is congruent with previous ecomorphological studies on waterfowl (Olsen 2017) 410

The transfer of grasping and manipulation behaviours from the forelimbs to the beak in 411 bird evolution has necessitated that bird beaks be highly versatile, used in virtually every aspect 412 of their biology, not just feeding and foraging (Bhullar et al. 2016). The complex evolutionary 413 scenario demonstrated by our results suggests that diverse and multidirectional selective 414 pressures were involved in beak morphological diversification, reflective of functional and 415 behavioural multitasking. In this evolutionary context, a fast, generic grabbing tool could most 416 easily fit the required compromise of functional versatility (i.e. trade-off between varied beak 417 functions), explaining the prevalence of thin and straight beak shapes and optimization for low-418 force transmission high-speed gapes in our sample. More nuanced relationships between 419 420 feeding adaptation and beak shape may be operating, with variable strength, within lower taxonomic levels, in order to accommodate different macroevolutionary regimes and trade-421 offs. For example, while a strong association between feeding ecology and beak shape 422 characterizes the diversification patterns within waterfowl (Olsen 2017), skull centroid size, 423 not diet, is a major driver of beak shape in diurnal raptors (Bright et al. 2016). Nevertheless, 424 our data support the idea that beak shape and mechanical advantage reflect the mechanical 425

demands of specific feeding and foraging strategies (Bowman 1961; Schwenk 2000). This 426 relationship may be best envisioned as a threshold rather than a one-to-one connection, with 427 certain shapes and mechanical properties critically needed to perform certain functions and 428 feeding behaviours (e.g., in order to avoid fracture). In agreement with these views, some 429 species of Darwin's finches show dietary habits and feeding strategies that are more flexible 430 than previously thought; their specialized beak phenotypes (e.g. cracking/biting) are still 431 432 efficient in processing many other dietary resources, which might lead to the evolutionary retention of these phenotypes (i.e. Liem's paradox; Tebbich et al. 2004). 433

434 In conclusion, our results imply that the relationship between beak shape and feeding ecology at a broad macroevolutionary scale may be more complex than usually assumed. This 435 is particularly important in fossil taxa, where trophic hypotheses are rarely testable (e.g., 436 fossilised gut contents). In light of these results, it is important to evaluate the strength of the 437 relationships between form, functional traits, and feeding behaviour within a taxonomic 438 context, before drawing trophic assumptions based solely on beak morphology. In doing so, 439 we will open pathways for a more detailed understanding of the role of trophic adaptation in 440 shaping avian diversity. 441

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- 680 Tables

Table 1. Allometric relationships between beak shape, anterior MA, and log-body mass. Summary of the PGLS linear models for Procrustes coordinates (beak shape) and anterior MA (functional trait) as a function of log-body mass (body size). Cells in bold indicate statistical significance (P < 0.05).

		Allometry			
686		Beak shape	Anterior MA		
	Statistic	log-BM	log-BM		
687	R^2	0.00559	0.03479		
	F	0.9727	6.2363		
688	Ζ	0.37606	1.3826		
689	Р	0.362	0.014		

Table 2. Summary of the PGLS linear models for Procrustes coordinates (beak shape), anterior MA (functional trait), log-body mass (body size) as a function of dietary preferences, and UBF categories (including main effects of both independent variables and their interaction). Cells in bold indicate statistical significance (P < 0.05). Effect sizes (Z) are computed as standard deviates of the F values' randomized sampling

695 distributions. *P* values are calculated for the *F* values' randomized sampling

696 distributions.

Type II (conditional SS)											
		Beak shape		Mechanical advantage		log BM					
	Statistic	Diet	UBF	Diet:UBF	Diet	UBF	Diet:UBF	Diet	UBF	Diet:UBF	
	R^2	0.1156	0.0923	0.22625	0.1692	0.0697	0.26376	0.2548	0.03927	0.21506	
	F	2.6229	4.1873	1.2837	4.7547	3.9192	1.8533	5.9806	1.8431	1.2619	
	Ζ	3.7041	3.8639	2.9112	3.4418	2.4523	3.0463	3.9382	1.4838	2.2405	
	Р	0.001	0.001	0.002	0.001	0.005	0.001	0.001	0.042	0.01	
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703 **Figure captions**

Figure 1. Species-level trophic variables and phylogenetic hypothesis. The dietary preferences for each species are quantified as the proportions of 10 food items that comprise taxon diet. UBF are categorical variables that reflect mechanical differences in use of the beak during feeding (SM. Figure 1). Numbers correspond to clades as detailed in SM. Table 2.

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Figure 2. Schematic overview of the main ecomorphological and functional associations
explored in this study by means of PGLS regressions and Phylogenetic MANOVA.
Concepts of biological role, behaviour, performance, and structure follow Lauder (1995). 1-3
= position of homologous landmarks; red line = in-lever; blue line = posterior out-lever; green
line = anterior out-lever.

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Figure 3. Morpho-functional landscape. A) Anterior MA values (a functional trait related 715 with bite force/gape speed transmission) overlaid as heat-map isozones over the 716 phylomorphospace of the first three Principal Components (phylogeny mapped over the scores 717 of PC1-3 by means of minimum least squares) of beak shape variation. B) Anterior MA values 718 mapped over our phylogenetic hypothesis, species labelled by use of beak during feeding 719 (UBF) category. Outlines for the extreme shapes along PC1 correspond to -0.25 and 0.25 720 scores; outlines for the extreme shapes along PC2 and PC3 correspond to scores of -0.15 and 721 722 0.15.

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Figure 4. Relationship between beak shape, diet, and use of beak during feeding (UBF).
PC1-3 plots with species labelled by main component of diet (categorical). Convex hulls
indicate the morphospace occupancy of each of the use of beak during feeding (UBF) groups:
dark grey (filled) = cracking/biting; red (filled) = tearing; blue (filled) = probing; orange

(dashed) = grabbing/gleaning; green (dashed) = pecking/grazing; light grey (filled) = filtering. 728 For the purposes of visualization every species is labelled with the categories reflecting the 729 main component of diet (sourced from Wilman et al. 2014). These categories were honed from 730 the original (Willman et al. 2014) for taxa where a single food component made up \geq 50% of 731 the diet composition and no other single food component made up the remaining 50%. For 732 instance, the Eurasian sparrowhawk (Accipiter nisus) is estimated by Wilman et al. (2014) to 733 feed on endothermic vertebrates 100% of the time and is scored therein as 'VertFishScav'; 734 here, it was re-scored as 'VertEnd' (SM. Table 1). 735

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Figure 5. Relationship between beak shape and function. PGLS regression of Procrustes coordinates on anterior mechanical advantage values (anterior MA). Decoupling between beak shapes and mechanical advantage from the general trend is more noticeable in deep and curved beaks. Grey shaded area represents the lower 20% of anterior MA values, where 80% of the species fall (80 percentile indicated by grey line). Bird species labelled by UBF category.

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Figure 6. Dietary preferences and their relationships with beak shape, anterior MA, and
body size. PGLS regression plots of the main axis of dietary variation in our sample (PCo1)
and regression scores for (from top to bottom): Procrustes coordinates (beak shape), Anterior
MA, and log-BM. Main component of diet categories are the same as Figure 3. See SM.Fig. 6
for the same relationships labelled by UBF group.

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753 Figures

754 **Figure 1.**















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