

Capital adjustment cost and inconsistency in income based dynamic panel models with fixed effects

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Abstract

After the seminal work of Nickell (1981), a vast literature demonstrate the inconsistency of "conditional convergence" estimator in income based dynamic panel models with fixed effects when the time horizon (T) is short but the sample of countries (N) is large. Less attention is given to the economic root of inconsistency of the fixed effects estimator when T is also large. Using a variant of the Ramsey growth model with long-run adjustment cost of capital, we demonstrate that the fixed effects estimator of such models could be inconsistent when T is large. This inconsistency arises because of the long-run adjustment cost of capital which gives rise to a negative moving average coefficient in the error term. Income convergence will be thus overestimated. We theoretically characterize the order of this inconsistency. Our Monte Carlo simulation demonstrates that the size of the bias is substantial and it is greater in economies with higher capital adjustment costs.

Key words:

Dynamic panel model, adjustment cost of capital, inconsistency, Ramsey growth model

JEL Classification: C5. D2. D9. O4. O5

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1. Introduction

In the empirical economic growth literature, a typical specification of an income based dynamic panel econometric model is (e.g., Barro and Sala-i-Martin, 2004, Ch. 11, pp.462):

$$\ln(y_{it}/y_{it-1}) = - (1 - e^{-\beta}) \ln y_{it-1} + \mathbf{x}_{it}\boldsymbol{\lambda} + \eta_i + u_{it} \quad (1)$$

where y_{it} is the income of the i th cross section unit at date t ; x_{it} denotes a $1 \times J$ vector of control and interest variables; $\boldsymbol{\lambda}$ is a $J \times 1$ parameter vector; η_i represents the fixed effects (FE) and u_{it} is the random disturbance term. The parameters β and $\boldsymbol{\lambda}$ summarize the list of parameters to be estimated. In the convergence literature, $\beta > 0$ is the crucial parameter of interest because it measures the coefficient of conditional convergence known as β -convergence. Such a concept is used to understand the convergence of countries or regions conditional on certain fundamentals.¹ A higher value of β indicates a faster rate of conditional convergence among the regions or countries studied.

Dynamic panel models with fixed effects have been widely employed in the literature for studying convergence among group of countries (e.g., Islam, 1995, Caselli et al., 1996 and Ho, 2006). In his seminal work, Nickell (1981) points out that fixed effects (FE) estimator of dynamic panel models is inconsistent when T is short but N is large but consistent when $T \rightarrow \infty$.²

¹See, for instance, Barro and Sala-i-Martin (2004, Ch. 11).

²A sizable econometric literature investigates the nature of this FE bias and possible remedies in dynamic panel data models. For instance, following the work of Nickell (1981), Kiviet (1995),

The present paper demonstrates the existence of economic roots that could lead to the FE bias in long-time dynamic panel models. In particular, in income based FE dynamic panel estimation, the convergence coefficient β could be inconsistent in the presence of an economic primitive such as capital adjustment cost even when T is sufficiently large. Such an adjustment cost by causing a sluggish adjustment of the capital stock in response to an idiosyncratic productivity shock could give rise to a negative moving average term in the error process resulting in a correlation between the lagged dependent variable and the error term.³ The empirical evidence abound that such adjustment cost of capital is present (Chirinko, 1993 and Hamermesh and Pfann, 1996).

The novelty of the paper lies in identifying an economic fundamental such as capital adjustment cost as a factor contributing to inconsistency of a well known estimator. Although there is a proliferation of econometric literature suggesting possible remedies for inconsistency, little attention is given in the literature in understanding the economic root behind the inconsistency in a dynamic FE regression. Our paper is an attempt in that direction.

The issue of inconsistency due to the presence of capital adjustment cost is not

Judson and Owen (1999) and Hahn and Kuersteiner (2002) examine this bias in short and long dynamic panel FE models. Arellano and Bond (1991), Arellano and Bover (1995), Blundell and Bond (1998, 2000) and Bond (2002) provide a handy way to correct the FE bias in short-time dynamic panel models applying internal instruments. However, these are also criticized as sensitive to "instrumental proliferation" (Roodman, 2009).

³Pesaran and Smith (1995) point out that inconsistency in the dynamic panel estimator can arise if the lagged dependent variable is correlated with the error term. They also point out that the standard corrections for serial correlation are unlikely to work because of the complexity of the error process. We demonstrate the error process can have a negative MA term due to the existence of an economic fundamental such as capital adjustment cost.

entirely uncommon in the literature. Caballero (1994) establishes that the OLS estimate of wealth elasticity to adjustment cost generally tends to be inconsistent in a small sample when capital adjustment cost is present in the model. He does not, however, explore the implication of capital adjustment cost for FE bias. To the best of our knowledge, our paper is the first attempt in the literature to understand the role of capital adjustment cost as an economic fundamental driving the inconsistency of convergence estimator in dynamic panel models with long time horizon.

To demonstrate our key point, we develop a standard Ramsey growth model with a convex capital adjustment cost function. Such an adjustment cost function means a rising marginal cost of investment. While diminishing returns to capital facilitate the process of convergence, a rising marginal cost of investment schedule slows it down. The usual dynamic panel FE regression model fails to factor into this capital adjustment cost and thus it overestimates the rate of convergence. We show this formally by establishing that the income based dynamic models has a negative first order moving average error when capital adjustment cost is present. A negative correlation between the lagged dependent variable $\ln y_{it-1}$ and the disturbance terms u_{it} in (1) makes the convergence coefficient inconsistent. In a multivariate context, we show that the efficiency of all coefficient estimators are affected by this inconsistency when the adjustment cost of capital is present.

We derive an analytical expression for the inconsistency employing the Ramsey growth model with a capital adjustment cost technology. A well known parametric form for the adjustment cost function is borrowed from Lucas and Prescott (1971) that was subsequently used by Basu (1987), Hercowitz and Sampson (1991) and Basu

et al. (2012). Such a capital adjustment cost differs from the investment adjustment cost (e.g. Christiano et al., 2005) in the sense that the adjustment cost persists even in the long-run. This explains why inconsistency arises even for infinite time horizon ($T \rightarrow \infty$). Our Monte Carlo experiment shows that inconsistency increases with the degree of the adjustment cost of capital and it is quantitatively substantial.

In the next section, we develop a Ramsey-type growth model with heterogeneous countries in terms of initial wealth, tastes and productivity to characterize the inconsistency due to the adjustment cost. Section 3 reports a Monte Carlo simulation to demonstrate the sensitivity of the FE bias to the adjustment cost. Section 4 concludes.

2. The model

2.1. Preference and technology

Consider a sequence of infinitely-lived heterogeneous representative citizens for each country, $i = 1, 2, \dots, N$ and $t = 1, 2, \dots, \infty$ where i stands for the country representative⁴ and t stands for time. Countries are heterogeneous in terms of (i) initial capital stock (k_{i0}), (ii) preference (discount factor, ρ_i) and (iii) idiosyncratic productivity shock (ξ_{it}).⁵ We let the preference parameter ρ_i vary across countries which could give rise to country specific fixed effects. Also, assume that cross country productivity shocks are iid. Households are further assumed to be both consumers

⁴Alternatively, i could represent a country in the world economy whereas each country is represented with a single representative consumer, as in Acemoglu and Ventura (2002).

⁵Variables with(out) subscript i represent individual (economy-wide) values. Variables without subscripts t and i represent economy-wide steady-state values.

and entrepreneurs.⁶

The production function facing the i th country resident is Cobb-Douglas with constant returns to scale as follows,

$$q_{it} = \xi_{it} \left(\prod_{j=1}^J (g_{ijt})^{\chi_j} \right) (k_{it})^\omega (m_{it})^\varphi \quad (2)$$

$$\varphi + \omega + \sum_{j=1}^J \chi_j = 1 \quad (3)$$

where q_{it} is the gross output of the i th country, k_{it} is the country's capital stock at period t and k_{i0} is given. g_{ijt} represents the j th exogenous input in the production function (such as infrastructure or a learning-by-doing knowledge spillover that could potentially give rise to technological externality, in the spirit of Arrow, 1962) that is specific to the i th country condition. In addition, m_{it} is a flow of imported intermediate inputs that the country finances by borrowing from the international credit market at a fixed interest rate, r^* . The i th country agent treats g_{ijt} as given while choosing consumption and investment. The production technology thus exhibits private diminishing returns to reproducible input k_{it} , imported intermediate input m_{it} and the exogenous inputs g_{ijt} but aggregate constant returns to scale, (similar to Romer, 1986 and Barro, 1990).⁷

The i th country borrows m_{it} at the start of each period and fully pays off the loan with interest rate at the end of each period. The optimal purchase of imported intermediate input thus satisfies the condition:

⁶See Angeletos and Calvet (2006) for a similar type of entrepreneurship.

⁷Barro (1990) models the production function at the individual firm level as a function of private and public capital.

$$\partial q_{it}/\partial m_{it} = 1 + r^* \quad (4)$$

which gives rise to the following demand function for intermediate inputs,

$$m_{it} = [\varphi/1 + r^*]^{1/(1-\varphi)} \left(\prod_{j=1}^J (g_{ijt})^{\chi_j/(1-\varphi)} \right) (k_{it})^{\omega/(1-\varphi)} (\xi_{it})^{1/(1-\varphi)} \quad (5)$$

which upon plugging into (2) and after netting out the loan retirement cost, $(1 + r^*) m_{it}$, gives the net value added (y_{it}),

$$y_{it} = \epsilon_{it} \left(\prod_{j=1}^J (g_{ijt})^{\lambda_j} \right) (k_{it})^\alpha \quad (6)$$

where

$$\begin{aligned} \epsilon_{it} &\equiv (1 - \varphi) (\varphi / (1 + r^*))^{\varphi/(1-\varphi)} (\xi_{it})^{1/(1-\varphi)} \\ \lambda_j &\equiv \chi_j / (1 - \varphi) \\ \alpha &\equiv \omega / (1 - \varphi) \end{aligned}$$

The i th country agent maximizes her utility in accordance to the utility function, with a subjective discount factor ρ_i :

$$E_0 \left[\sum_{t=0}^{\infty} (\rho_i)^t \ln c_{it} \right]; \rho_i < 1 \quad (7)$$

subject to the budget constraint,

$$c_{it} + s_{it} = y_{it} \tag{8}$$

where c_{it} and s_{it} represent consumption and saving, respectively.

Following Lucas and Prescott (1971), Basu (1987) and Basu et al. (2012), the investment technology is given by the following specification:

$$k_{it+1} = k_{it} (1 - \delta + s_{it}/k_{it})^\theta \tag{9}$$

where $\delta \in (0, 1)$ and $\theta \in (0, 1)$ are rate of depreciation and degree of adjustment cost of capital (k_{it}), respectively. If $\theta = 0$, adjustment cost of capital is prohibitively high to change the capital stock. However, if $\theta = 1$, adjustment cost of capital is zero and we obtain a standard linear depreciation rule. We focus on such capital adjustment costs between these two extremes costs because it has important implications for the reduced form process for the per capita income.

Supposing capital depreciates fully each period, we may rewrite (9) as:⁸

$$k_{it+1} = k_{it} (s_{it}/k_{it})^\theta \tag{10}$$

Applying standard methods of undetermined coefficient, the optimal policy functions for the i th agent are simplified as follows, (see Appendix A for details of the derivation),⁹

⁸We assume complete depreciation of capital for analytical tractability, without loss of generality. Basu and Getachew (2014) show that depreciation cost has a trivial effect on convergence property.

⁹See also, Basu (1987) and Hercowitz and Sampson (1991) for a similar closed form solution.

$$c_{it} = (1 - \psi_i) y_{it} \quad (11a)$$

$$s_{it} = \psi_i y_{it} \quad (11b)$$

where

$$\psi_i \equiv \theta \alpha \rho_i / (1 - \rho_i (1 - \theta)) \quad (12)$$

After substituting (6) and (11b) into (10), the optimal dynamic equation of capital stock of the i th country resident is given by,

$$k_{it+1} = (\psi_i)^\theta (k_{it})^\gamma \left(\prod_{j=1}^J (g_{ijt})^{\lambda_j} \right)^\theta (\epsilon_{it})^\theta \quad (13)$$

where $\gamma \equiv 1 - (1 - \alpha) \theta$. Therefore, the optimal capital stock in period $t + 1$ for country i is a function of the country's current capital stock (k_{it}), the idiosyncratic shock (ϵ_{it}), time-dependent country specific exogenous factors (g_{ijt}) and a time-independent country specific factor (ψ_i), and adjustment cost of capital θ .

2.2. Role of long-run adjustment cost in determining the bias

According to (13), the adjustment cost of capital ($\theta \neq 1$) impacts not only the dynamics of capital at the individual country level but also the steady-state capital.¹⁰ In this respect, it differs from investment adjustment cost as in Christiano et al.

¹⁰Note that in the present model, the country specific fixed effect arises solely due to differences in the taste parameter ρ_i . A more general specification can allow for differences in technology which we do not pursue here.

(2005) which do not have such long run effects.¹¹ In particular, we see below the long-run variance of the capital stock is given by $v^2\theta^2 / (1 - \gamma^2)$ where $v^2 = \text{var} [\ln \epsilon_{it}]$, which depend on the adjustment cost parameter θ .¹² Thus the adjustment cost does not disappear in the long-run when $(\theta \neq 1)$.

In the present context, this long-lasting nature of the adjustment cost is particularly reflected on its effect on the idiosyncratic shock. First, this idiosyncratic shock forms the disturbance term (u_{it}) in an estimation equation (1). Second, the shock relates to country's contemporaneous income (6), which appears as a lagged variable in dynamic panel regression models. Therefore, such effects of the idiosyncratic shock will manifest as a source of inconsistency in the estimate of the lagged income in (1).

Based on the production function (6), the log of income of the i th country at date t is given by,

$$\begin{aligned} \ln y_{it} &= \alpha \ln k_{it} + \sum_{j=1}^J (\lambda_j \ln g_{ijt}) + \ln \epsilon_{it} \\ &= \alpha \ln k_{it} + \mathbf{g}_{it} \boldsymbol{\lambda} + \ln \epsilon_{it} \end{aligned} \tag{14}$$

where \mathbf{g}_{it} is $1 \times J$ vector of (exogenous) regressors, $\mathbf{g}_{it} \equiv (\ln g_{i1t}, \ln g_{i2t}, \dots, \ln g_{iJt})$ and $\boldsymbol{\lambda} \equiv (\lambda_1, \lambda_2, \dots, \lambda_J)'$ is a $J \times 1$.

Finally, applying (6) and (13) to (14), we obtain the following representation for

¹¹See Groth and Khan (2010) for a specification of a general adjustment cost function which nests capital and investment adjustment cost.

¹²Refer to Corollary 1 below for details of the derivation of the variance.

the dynamic panel model:

$$\ln y_{it} = \gamma \ln y_{it-1} + \sum_{j=1}^J \lambda_j x_{ijt} + \eta_i + u_{it} \quad (15)$$

where $\eta_i \equiv \alpha \theta \ln \psi_i$ and,

$$x_{ijt} \equiv (\theta - 1) \ln g_{ijt-1} + \ln g_{ijt} \quad (16a)$$

$$u_{it} = \ln \epsilon_{it} - (1 - \theta) \ln \epsilon_{it-1} \quad (16b)$$

In vector form,

$$\ln y_{it} = \gamma \ln y_{it-1} + \mathbf{x}_{it} \boldsymbol{\lambda} + \eta_i + u_{it} \quad (17)$$

where $\mathbf{x}_{it} \equiv (x_{i1t}, x_{i2t}, \dots, x_{iJt})$ is a $1 \times J$, $\boldsymbol{\lambda} \equiv (\lambda_1, \lambda_2, \dots, \lambda_J)'$ as x_{ijt} is defined in (16a) while u_{it} is given by (16b). By virtue of (1), one can write $-(1 - \gamma) = -(1 - e^{-\beta})$. Then, using the linear approximation that $e^{-\beta} \approx 1 - \beta$ one gets:

$$1 - \gamma = \beta \quad (18)$$

Thus, the higher the value of γ , the slower the convergence.

Eq. (17) is an ARMA (1,1) evolution of the income of the i th country which looks similar to (1). It represents the true specification for the estimation model of conditional convergence based on the Ramsey growth model with a non-zero long-run adjustment cost of capital. Such adjustment cost can be seen as a permanent tax

on capital imposed by the mother nature. The long-run impact of such idiosyncratic shock (13) is responsible for the negative moving average disturbance term (u_{it}) in (17).

The income based dynamic panel regression model thus involves an error term which is negatively correlated with the lagged dependent variable ($\ln y_{it-1}$). Therefore, the dynamic panel estimators with FE γ are inconsistent, even when $T \rightarrow \infty$.

To see the order of inconsistency involved in the lagged income term, set $\lambda_j = 0$ for all j to simplify exposition. Then, the following Proposition and Corollary can be stated for the univariate case:

Proposition 1. *The inconsistency from the dynamic panel model with FE estimator ($\hat{\gamma}$) of the coefficient γ with respect to (17), when $\forall j \lambda_j = 0$, is given by:*

$$p \lim (\hat{\gamma}) = \gamma + [(\theta - 1) v^2 / \mathbf{E}_i \text{var} \{\ln y_{it-1}\}] \quad (19)$$

where $v^2 = \text{var}(\epsilon_{it})$.

Proof. See Appendix B. ■

Corollary 1. *The size of the bias is given by*

$$\Phi \equiv \frac{(1 - \gamma^2)(1 - \theta)}{\alpha^2 \theta^2 + (1 - \gamma^2)}. \quad (20)$$

Proof. Using (14), when $\forall j \lambda_j = 0$, we can rewrite the denominator in (19) as,

$$\begin{aligned} \mathbf{E}_i \text{var} [\ln y_{it-1}] &= \mathbf{E}_i \text{var} [\alpha \ln k_{it-1} + \ln \epsilon_{it-1}] \\ &= \alpha^2 \mathbf{E}_i \text{var} [\ln k_{it-1}] + v^2 \end{aligned} \quad (21)$$

Then, from (13),

$$\begin{aligned} \mathbb{E}_i \text{var} [\ln k_{it-1}] &= \mathbb{E}_i \text{var} [\ln \eta_i + \gamma \ln k_{it-2} + \theta \ln \epsilon_{it-2}] \\ &= \gamma^2 \mathbb{E}_i \text{var} [\ln k_{it-2}] + \theta^2 v^2 \end{aligned} \quad (22)$$

since η_i is fixed over time and $\text{cov}(\ln k_{it}, \ln \epsilon_{it}) = 0$. Next note from (13) that for a generic i th country agent, $\lim_{t \rightarrow \infty} \text{var} [\ln k_{it-1}] = \text{var} [\ln k_{it-2}] = v^2 \theta^2 / (1 - \gamma^2)$ because $0 < \gamma < 1$.¹³ Since α, v^2 and θ are the same for all i , all agents converge to the same variance of the capital stock which implies

$$\mathbb{E}_i \text{var} [\ln k_{it-1}] = v^2 \theta^2 / (1 - \gamma^2) \quad (23)$$

Substitute (21) into (19) after substituting (23) into the former to derive the closed form solution for the degree of inconsistency. ■

Thus in the presence of capital adjustment cost in a growth model, the panel estimator with FE of γ in (1) is inconsistent regardless of the time dimension of the panel. This overestimates the conditional convergence. It is straightforward to verify that this bias is greater in economies with a lower value of θ meaning a higher adjustment cost. The inconsistency of the FE estimator is absent if there is no capital adjustment cost ($\theta = 1$).

¹³To see this, rewrite (22) as:

$$\begin{aligned} \mathbb{E}_i \text{var} [\ln k_{it}] &= \gamma^{2T} \mathbb{E}_i \text{var} [\ln k_{i0}] + \theta^2 v^2 \sum_{t=0}^{T-1} \gamma^{2t} \\ &= \gamma^{2T} \mathbb{E}_i \text{var} [\ln k_{i0}] + \theta^2 v^2 (1 - \gamma^{2T+2}) / (1 - \gamma^2) \end{aligned}$$

As $T \rightarrow \infty$, the terms in the right hand side converge to $v^2 \theta^2 / (1 - \gamma^2)$.

The inconsistency of the FE estimator arises due to a negative contemporaneous correlation between $\ln y_{it-1}$ and $\ln \epsilon_{it-1}$. The size of this correlation is proportional to the degree of adjustment cost $(1 - \theta)$. To get the (economic) intuition further for such a negative correlation, let the i th country experience a positive TFP shock ($\Delta \ln \epsilon_{it-1}$ %) at date $t - 1$. The optimal investment rule (11b) dictates that the i th country resident's contemporaneous investment rises by the same percent because the elasticity of s_{it-1} with respect to ϵ_{it-1} is unity. Such a blip in investment ($\Delta \ln s_{it-1}$) increases the current capital stock ($\ln k_{it}$) by only θ % (see 10). The remaining $(1 - \theta)$ % of the investment is lost due to the presence of the long-run capital adjustment cost. This loss enters the error term in (17) with a negative coefficient $-(1 - \theta) \ln \epsilon_{it-1}$. The standard regression equation (1) ignores this negative correlation between $\ln y_{it-1}$ and $\ln \epsilon_{it-1}$. As a result, the estimate of γ will be inconsistent and, hence, the "conditional convergence" will be overestimated.

In the multivariate case where $\exists j \lambda_j \neq 0$, the inconsistency in FE panel estimator affects the estimators of all variables due to a correlation between lagged output and exogenous technological variables. Proposition 2 below demonstrates this.

Proposition 2. *The inconsistency from the dynamic panel model with FE estimator of $\hat{\gamma}$ and $\hat{\lambda}$ of the parameters γ and λ with respect to (17) are given by, when $\exists j \lambda_j \neq 0$:*

$$p \lim \left(\hat{\lambda} \right) = \tilde{\lambda} + (\mathbf{E}_i \mathbf{E} [\mathbf{b}'_{it} \mathbf{b}_{it}])^{-1} \mathbf{p}(\theta - 1)v^2 \quad (24)$$

where $\mathbf{b}_{it} \equiv \tilde{\mathbf{x}}_{it} - \tilde{\mathbf{x}}_i$, $\tilde{\lambda} \equiv (\gamma, \lambda)'$, $\mathbf{p} \equiv (1, \mathbf{0})'$ and $\mathbf{0}$ is $1 \times J$ zero vector.

Proof. See Appendix C. ■

The last term in (24) is different from zero with a non-zero adjustment cost of capital ($\theta \neq 1$). Therefore, in the multivariate case the efficiency of all coefficient

estimators (17) are affected by the inconsistency when the adjustment cost of capital is present. This happens because the lagged income is correlated with the exogenous variables in the production function.

3. Simulation

In this section, we report the results of a Monte Carlo simulation based on our ARMA(1,1) specification of the income process (15) to ascertain the quantitative magnitude of the bias resulting from the capital adjustment. As in our model income process (17), we allow the subjective discount factor ρ_i to vary across countries in the range $[0.9, 0.99]$ which is the source of the fixed effect. All other structural parameters are assumed to be the same for all countries. The capital elasticity parameter α is fixed at 0.9 which is higher than the conventional level of 0.36 with a view to target a plausible rate of convergence. The higher value of α is not unreasonable in an open economy context given the fact that α equals $\omega/(1 - \varphi)$ which could be higher if the share φ of foreign intermediate input is higher. In addition, Romer (1986) alludes to a higher capital share estimate in view of the broad based nature of capital that includes knowledge. The adjustment cost parameter is first fixed at a baseline level of 0.2 which gives rise to a γ equal to 0.98 meaning a 2% conditional convergence (see 18) which is in accord with Barro and Sala-i-Martin (2004).

For a fixed i , we take 10000 draws of TFP (ϵ_{it}) from an iid lognormal distribution and pass it through the true ARMA (1,1) process (17) for income (normalizing the initial income at the unit level) to generate draws of $\log y_{it}$. We take 1000 draws of ρ_i from a rectangular distribution with the support $[0.9, 0.99]$ to capture the fixed

Table 1: Sensitivity of the bias to alternative θ values

θ	γ	$p \lim(\hat{\gamma})$	Bias
0.2	0.98	0.5437	0.4363
0.4	0.96	0.7331	0.2269
0.6	0.94	0.8259	0.1141
0.8	0.92	0.8740	0.0460
1.00	0.90	0.90	0.0000

effects. The pooled estimator (B.8) as shown in the appendix is then computed for sufficiently large T and N . The bias (the difference between γ and $\hat{\gamma}$) is about 0.44 for the baseline case. The failure to include the adjustment cost could potentially give rise to an overestimation of convergence by 44%. Table 1 illustrates the sensitivity of the bias to alternative adjustment cost parameter values. The bias decreases in economies with lower adjustment cost (higher θ). For no adjustment cost scenario, the bias nearly disappears.

4. Conclusion

The economic fundamentals that could generate inconsistency in models have rarely received any attention in macroeconometrics literature. Such inconsistency could arise due to several economic fundamentals. We identify one such fundamental in income based dynamic panel models which is the long-run capital adjustment cost. Using a parametric form for such an adjustment cost technology in a standard Ramsey growth model, we have demonstrated that the dynamic panel regression with fixed individual effects gives rise to an inconsistent estimator of convergence for an infinite time horizon. The inconsistency arises because of the presence of a

negative moving average term in the error of the dynamic panel regression. The inconsistency is larger in economies with a higher adjustment cost of capital which is verified in a Monte Carlo simulation. The implication of this inconsistency is that the FE estimator of the "conditional convergence" of countries or regions could seriously overestimate convergence.

A future extension of this paper would be exploring remedy for this FE estimator bias resulting from capital adjustment cost. Moreover, our analysis is based on a specific functional form for the capital adjustment cost technology that admits a closed form solution for the reduced form income process. Such a specific functional form is employed to derive an analytical solution for the FE bias and show how it depends on the capital adjustment cost. Future extension of our work would be to take a more general adjustment cost specification which includes short run investment adjustment cost such as Christiano et al. (2005) and explore the inconsistency implications.

Appendix

A. Optimal capital accumulation

The proof mimics Basu (1987). Write the value function for this problem as:

$$v(k_{it}, \epsilon_{it}, g_{i1t}, \dots, g_{iJt}) = \max_{k_{it+1}} \left[\ln \left\{ \epsilon_{it} \left(\prod_{j=1}^J (g_{ijt})^{\lambda_j} \right) (k_{it})^\alpha - (k_{it+1}/k_{it})^{1/\theta} k_{it} \right\} \right. \\ \left. + \rho_i E_t v(k_{it+1}, \epsilon_{it+1}, g_{i1t+1}, \dots, g_{iJt+1}) \right]$$

where E_t is the conditional expectation operator.

Conjecture that the value function is loglinear in state variables as follows:

$$v(k_{it}, \epsilon_{it}) = \pi_0 + \pi_1 \ln k_{it} + \pi_2 \ln \epsilon_{it} + \pi_3 \sum_{j=1}^J \lambda_j \ln g_{ijt}$$

which after plugging into the value function

$$\begin{aligned} & \pi_0 + \pi_1 \ln k_{it} + \pi_2 \ln \epsilon_{it} + \pi_3 \sum_{j=1}^J \lambda_j \ln g_{ijt} \\ &= \max_{k_{it+1}} \left[\begin{array}{l} \ln \left\{ \epsilon_{it} \left(\prod_{j=1}^J (g_{ijt})^{\lambda_j} \right) (k_{it})^\alpha - (k_{it+1}/k_{it})^{1/\theta} k_{it} \right\} \\ + \rho_i \mathbb{E}_t \left\{ \pi_0 + \pi_1 \ln k_{it+1} + \pi_2 \ln \epsilon_{it+1} + \pi_3 \sum_{j=1}^J \lambda_j \ln g_{ijt+1} \right\} \end{array} \right] \end{aligned} \quad (\text{A.1})$$

Differentiating with respect to k_{it+1} and rearranging terms one gets:

$$k_{it+1} = [(\pi_1 \rho_i \theta / (1 + \pi_1 \rho_i \theta))]^\theta (\epsilon_{it})^\theta \left(\prod_{j=1}^J (g_{ijt})^{\lambda_j} \right)^\theta (k_{it})^{\alpha \theta + 1 - \theta} \quad (\text{A.2})$$

which after plugging into (A.1) and comparing left hand and right side coefficients of $\ln k_{it}$ uniquely solves:

$$\pi_1 = \alpha / (1 - \rho_i (\alpha \theta + 1 - \theta))$$

which after plugging into (A.2) we get:

$$k_{it+1} = \{\alpha \rho_i \theta / (1 - \rho_i (1 - \theta))\}^\theta (\epsilon_{it})^\theta \left(\prod_{j=1}^J (g_{ijt})^{\lambda_j} \right)^\theta (k_{it})^{\alpha \theta + 1 - \theta} \quad (\text{A.3})$$

Note that the decision rule for the capital stock depends only on π_1 . The remaining coefficients, π_0 , π_2 and π_3 can also be solved by using the same method of undetermined coefficients and one can check that they are also uniquely determined

by π_1 .

B. Proof of proposition 1

First rewrite (17), when $\forall j \lambda_j = 0$, as:

$$\ln y_{it} = \gamma \ln y_{it-1} + \eta_i + u_{it} \quad (\text{B.4})$$

where u_{it} is given by (16b). Then, rewrite (B.4) in a deviation (from individual steady-state mean) form as follows to eliminate the unobserved individual heterogeneity (η_i):

$$a_{it} = \gamma a_{it-1} + v_{it} \quad (\text{B.5})$$

where

$$a_{it} \equiv \ln y_{it} - \ln y_i \text{ and } a_{it-1} \equiv \ln y_{it-1} - \ln y_{i-1} \quad (\text{B.6})$$

$$v_{it} \equiv (\theta - 1) (\ln \epsilon_{it-1} - \ln \epsilon_{i-1}) + (\ln \epsilon_{it} - \ln \epsilon_i) \quad (\text{B.7})$$

For any z , $\ln z_i \equiv (T - 1)^{-1} \sum_{t=1}^{T-1} \ln z_{it}$ and $\ln z_{i-1} \equiv T^{-1} \sum_{t=1}^T \ln z_{it-1}$.

The FE estimator of γ is the pooled OLS estimator of the model (B.5),

$$p \lim (\hat{\gamma}) = \frac{\sum_{i=1}^N \sum_{t=1}^T (a_{it} a_{it-1})}{\sum_{i=1}^N \sum_{t=1}^T a_{it-1}^2} = \gamma + \frac{\sum_{i=1}^N T^{-1} \sum_{t=1}^T (v_{it} a_{it-1})}{\sum_{i=1}^N T^{-1} \sum_{t=1}^T a_{it-1}^2} \quad (\text{B.8})$$

When $T \rightarrow \infty$, the terms in the right side of (B.8) can be rewritten as,

$$p \lim (\hat{\gamma}) = \gamma + \sum_{i=1}^N \mathbf{E} [v_{it} a_{it-1}] / \sum_{i=1}^N \mathbf{E} [a_{it-1}^2] \quad (\text{B.9})$$

where $\mathbf{E}(\cdot)$ stands for the time expectation operator.

Substituting back (B.6) into (B.9), we obtain,

$$\begin{aligned} p \lim (\hat{\gamma}) &= \gamma + \frac{\sum_{i=1}^N \mathbf{E} [(\ln y_{it-1} - \mathbf{E} [\ln y_{it-1}]) ((\theta - 1) \ln \epsilon_{it-1} + \ln \epsilon_{it})]}{\sum_{i=1}^N \mathbf{E} [(\ln y_{it-1} - \mathbf{E} [\ln y_{it-1}]) (\ln y_{it-1} - \mathbf{E} [\ln y_{it-1}])]} \\ &= \gamma + \sum_{i=1}^N \text{cov} ((\ln y_{it-1}, (\theta - 1) \ln \epsilon_{it-1} + \ln \epsilon_{it}) / \sum_{i=1}^N \text{var} [\ln y_{it-1}]) \end{aligned} \quad (\text{B.10})$$

Note that from (6), $\text{cov}(\ln y_{it-1}, \ln \epsilon_{it}) = 0$.¹⁴ Thus, (B.10) becomes

$$p \lim (\hat{\gamma}) = \gamma + (\theta - 1) \sum_{i=1}^N \text{cov}(\ln y_{it-1}, \ln \epsilon_{it-1}) / \sum_{i=1}^N \text{var}(\ln y_{it-1}) \quad (\text{B.11})$$

Then, substitute (6) into (B.11) to obtain,

$$\begin{aligned} p \lim (\hat{\gamma}) &= \gamma + (\theta - 1) \text{cov}(\alpha \ln k_{it-1} + \ln \epsilon_{it-1}, \ln \epsilon_{it-1}) / \text{var} (\ln y_{it-1}) \\ &= \gamma + (\theta - 1) N^{-1} \sum_{i=1}^N \text{var}(\ln \epsilon_{it-1}) / N^{-1} \sum_{i=1}^N \text{var} (\ln y_{it-1}) \end{aligned} \quad (\text{B.12})$$

since k_{it-1} is predetermined and, hence, uncorrelated with ϵ_{it-1} (see (6)).

Taking $N \rightarrow \infty$, (B.12) can be rewritten as:

¹⁴This is also referred as sequential exogeneity (see Wooldridge, 2010, Ch. 10 & 11).

$$p \lim (\hat{\gamma}) = \gamma + (\theta - 1) E_i \text{var}(\ln \epsilon_{it-1}) / E_i \text{var}(\ln y_{it-1}) \quad (\text{B.13})$$

where $E_i(\cdot)$ represents the cross sectional expectation. Since $\text{var}(\ln \epsilon_{it-1}) = v^2$ is the same for all i , $E_i \text{var}(\ln \epsilon_{it-1}) = v^2$.

C. The multivariate case

For the case $\exists j \lambda_j \neq 0$, first rewrite (17) as:

$$\ln y_{it} = \tilde{\mathbf{x}}_{it} \tilde{\boldsymbol{\lambda}} + \eta_i + u_{it} \quad (\text{C.14})$$

where $\tilde{\mathbf{x}}_{it} \equiv (\ln y_{it-1}, \mathbf{x}_{it})$ is a $1 \times (J + 1)$ and $\tilde{\boldsymbol{\lambda}} \equiv (\gamma, \boldsymbol{\lambda})'$ is a $(J + 1) \times 1$ vector of parameters.

Then, transform the equation in (C.14) to eliminate the fixed effects (η_i):

$$a_{it} = \mathbf{b}_{it} \tilde{\boldsymbol{\lambda}} + v_{it} \quad (\text{C.15})$$

where $\mathbf{b}_{it} \equiv \tilde{\mathbf{x}}_{it} - \tilde{\mathbf{x}}_i$.

Recall that:

$$a_{it} \equiv \ln y_{it} - \ln y_i \quad (\text{C.16a})$$

$$v_{it} \equiv (\theta - 1) (\ln \epsilon_{it-1} - \ln \epsilon_{i-1}) + (\ln \epsilon_{it} - \ln \epsilon_i) \quad (\text{C.16b})$$

$$\tilde{\mathbf{x}}_{it} \equiv (\ln y_{it-1}, \mathbf{x}_{it}) \quad (\text{C.16c})$$

$$\begin{aligned} \mathbf{x}_{it} &\equiv (x_{i1t}, x_{i2t}, \dots, x_{iJt}) \\ &= (\theta - 1) \mathbf{g}_{it-1} + \mathbf{g}_{it} \end{aligned} \quad (\text{C.16d})$$

$$x_{ijt} \equiv (\theta - 1) \ln g_{ijt-1} + \ln g_{ijt} \quad (\text{C.16e})$$

$$\mathbf{g}_{it} \equiv (\ln g_{i1t}, \ln g_{i2t}, \dots, \ln g_{iJt}) \quad (\text{C.16f})$$

$$\tilde{\boldsymbol{\lambda}} \equiv (\gamma, \lambda_1, \lambda_2, \dots, \lambda_J)' \quad (\text{C.16g})$$

$$\begin{aligned} \mathbf{b}_{it} &= (\ln y_{it-1} - \ln y_{i-1}, x_{i1t} - x_{i1}, \dots, x_{iJt} - x_{iJ}) \\ &\equiv (b_{i0t}, b_{i1t}, \dots, b_{iJt}) \end{aligned} \quad (\text{C.16h})$$

The FE estimator of $\tilde{\boldsymbol{\lambda}}$ is the pooled OLS estimator of the model (C.15):

$$\begin{aligned} p \lim \left(\hat{\tilde{\boldsymbol{\lambda}}} \right) &= \left(\sum_{i=1}^N \sum_{t=1}^T (\mathbf{b}'_{it} \mathbf{b}_{it}) \right)^{-1} \sum_{i=1}^N \sum_{t=1}^T (\mathbf{b}'_{it} a_{it}) \\ &= \tilde{\boldsymbol{\lambda}} + \left(\sum_{i=1}^N T^{-1} \sum_{t=1}^T (\mathbf{b}'_{it} \mathbf{b}_{it}) \right)^{-1} \sum_{i=1}^N T^{-1} \sum_{t=1}^T (\mathbf{b}'_{it} v_{it}) \end{aligned} \quad (\text{C.17})$$

When $T \rightarrow \infty$, the terms in the right hand side of (C.17) can be rewritten as,

$$p \lim \left(\hat{\tilde{\boldsymbol{\lambda}}} \right) = \tilde{\boldsymbol{\lambda}} + \left(\sum_{i=1}^N \mathbf{E} [\mathbf{b}'_{it} \mathbf{b}_{it}] \right)^{-1} \sum_{i=1}^N \mathbf{E} [\mathbf{b}'_{it} v_{it}] \quad (\text{C.18})$$

Note that, the variance and covariance matrix is given by,

$$\mathbf{b}'_{it}\mathbf{b}_{it} = \begin{bmatrix} b_{i0t}^2 & b_{i0t}b_{i1t} & \dots & b_{i0t}b_{iJt} \\ b_{i1t}b_{i0t} & b_{i1t}^2 & \dots & b_{i1t}b_{iJt} \\ \cdot & \cdot & \dots & \cdot \\ b_{iJt}b_{i0t} & b_{iJt}b_{i1t} & \dots & b_{iJt}^2 \end{bmatrix}$$

and, considering that x_{ijt} are exogenous and thus $E[x_{ijt}v_{it}] = 0$, we can simplify the last term in (C.18) as,

$$E[\mathbf{b}'_{it}v_{it}] = (\theta - 1) \text{cov}(\ln y_{it-1}, \ln \epsilon_{it-1}) \mathbf{p} \quad (\text{C.19})$$

where $\mathbf{p} \equiv (1, \mathbf{0})'$ and $\mathbf{0}$ is $1 \times J$ zero vector.

Substituting (C.19) into (C.18), we obtain:

$$p \lim \left(\widehat{\boldsymbol{\lambda}} \right) = \widetilde{\boldsymbol{\lambda}} + (E_i E[\mathbf{b}'_{it}\mathbf{b}_{it}])^{-1} \mathbf{p}(\theta - 1)v^2 \quad (\text{C.20})$$

since, from Appendix B, $\text{cov}(\ln y_{it-1}, \ln \epsilon_{it-1}) = v^2$.

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