# Density stratification controls the bedform phase diagram of saline-gravity currents versus open-channel flows

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### Associate Editor – Kyle Straub

### Short Title – Bedform phase diagram for saline-gravity currents

Keywords: Bedforms, bedform phase diagram, density stratification, gravity currents, openchannel flows

This article has been accepted for publication and undergone full peer review but has not been through the copyediting, typesetting, pagination and proofreading process which may lead to differences between this version and the Version of Record. Please cite this article as doi: 10.1111/sed.13075

#### ABSTRACT

Sedimentary bedforms such as ripples and dunes are generated both by river flows and sediment-laden gravity currents. Gravity current deposits are usually parameterized using existing bedform phase diagrams which are based on data from laboratory experiments and field observations of open-channel flows. Yet, it is not evident that open-channel flow bedform phase diagrams are applicable to gravity current deposits. Gravity current hydrodynamics are dependent on vertical density variation, i.e. density stratification, and therefore are fundamentally different from open-channel flows. New experiments to produce gravity current deposits are conducted and compared to existing open-channel flow data. It is shown that a parameter phase-space based on the lower layer of stratified gravity currents (i.e. that part below the velocity maximum) significantly improves the prediction of bedform type compared to bedform phase diagrams derived from layer-averaged parameters. These results confirm that bedforms produced by gravity currents can only be accurately predicted using the Accept characteristics of the lower layer of stratified flow.

#### INTRODUCTION

Bedforms are topographic features produced by interactions between flow and sediment transport. They are observed in various natural settings such as rivers (e.g. Hendershot *et al.*, 2016), deserts (e.g. Lancaster, 1988), and snowpack (e.g. Filhol and Sturm, 2015). Further, extraterrestrial bedforms have been found on Mars, Venus, Titan, and Pluto (e.g. Telfer *et al.*, 2018). Relationships among the flows, sediment particles, and bedforms have been investigated for over a century (Owens, 1908). Empirical knowledge of bedforms is needed to predict risk in river engineering (e.g. Ashworth *et al.*, 2000). Because sedimentary structures, such as cross-lamination and parallel lamination, are recorded in deposits produced by the movement of bedforms (Harms, 1979), bedforms recorded in deposits also provide an archive of palaeoflow conditions. Based on laboratory and field observations, the relationships between hydraulic conditions and bedforms have been described via bedform phase diagrams for open-channel flows (e.g. van den Berg and van Gelder, 1993; Ohata *et al.*, 2017).

As well as rivers, dilute submarine gravity currents, such as turbidity currents or saline flows, develop bedforms (e.g. Flood *et al.*, 2009; Hughes Clarke, 2016; Hage *et al.*, 2018). Turbidity currents are particle-laden flows that are principal agents for transport of sediments from continental shelves to deep seas. These currents may erode and deposit significant amounts of sediments and thereby create deep-sea landscapes, for example, submarine canyons and submarine fans (e.g. Normark *et al.*, 2002; Dorrell *et al.*, 2015; Tubau *et al.*, 2015). Turbidity currents also transport organic carbon (Galy *et al.*, 2007; Liu *et al.*, 2012) and microplastics into deep seas (Kane and Clare, 2019). Deposits of turbidity currents (i.e. turbidites) are often observed in outcrops (e.g. Brooks *et al.*, 2018; Cornard and Pickering, 2019), and may exhibit cross-lamination and parallel

lamination (Bouma, 1962). In order to analyze turbidites, Baas *et al.* (2000) utilized a bedform phase diagram for open-channel flows.

Although submarine gravity currents are analogous to subaerial open-channel flows in terms of the ability to create bedforms and landscapes, the hydraulic properties of gravity currents differ from those of open-channel flows. For example, the density contrast of flows to ambient fluids is largely different between typical submarine gravity currents and open-channel flows. As a result, Kelvin-Helmholtz instability can occur at the upper boundary surfaces of gravity currents, while those of open-channel flows are stable due to a large density difference between air and water (Britter and Simpson, 1978). The interface instabilities lead the ambient water entrainment into the gravity currents.

As a result of ambient water entrainment, the vertical velocity structure of the flow is largely different between open-channel and turbidity currents. Velocity of openchannel flows monotonically increases with height (Fig. 1A), and the velocity profile in the near-bed region follows a logarithmic law (Nezu and Rodi, 1986). In contrast, the velocity of gravity currents reduces to zero at both the bed and the interface with ambient fluids (Fig. 1B).

The height of the velocity maximum,  $H_{\rm m}$ , naturally separates gravity currents into lower and upper shear layers (Altinakar *et al.*, 1996; Xu, 2010; Dorrell *et al.*, 2019). In this paper, the regions below and above  $H_{\rm m}$  are referred to as the 'lower layer' and 'upper layer', respectively (Fig. 1B). Previous experiments have shown that over short time and length scale flow velocity in the lower layer develops a logarithmic profile and that in the upper layer has a Gaussian-like profile (e.g. Kneller *et al.*, 1999; Hosseini *et al.*, 2006). Over long time and length scale, inherent to natural gravity currents, these profiles do not necessarily hold (Dorrell et al., 2019).

Despite its bipartite velocity structure, the mechanics of gravity currents have been often parameterized by the variables that are averaged from the bed to the ambient interface for simplicity (e.g. Ellison and Turner, 1959; Parker *et al.*, 1986). Hereafter, the layer represented using the layer-averaged parameters is referred to as the 'whole layer'. It should be noted, however, that gravity currents would be predicted to thicken inordinately downstream due to the entrainment of ambient water using existing layer-averaged models of gravity currents (Luchi *et al.*, 2018). This means that the vertical structure of the flow should be included in the analysis to capture the mechanics of gravity currents.

Considering the difference in hydraulic conditions and resultant behaviours of flows, it is not evident that conditions for formation of bedforms beneath unidirectional openchannel flows are applicable to gravity current deposits. Technological advances have enabled more direct observations of submarine gravity currents and bathymetric surveys of their deposits in recent years (Dorrell *et al.*, 2014, 2016; Hughes Clarke, 2016; Paull *et al.*, 2018; Gales *et al.*, 2019; Vendettuoli *et al.*, 2019), but there is still a paucity of data pertaining to bedforms produced by gravity currents (Dorrell *et al.*, 2019). Physical experiments have provided some detail on the process of submarine bedform formation (Sequeiros *et al.*, 2010a; Fedele *et al.*, 2016; Koller *et al.*, 2017, 2019). However, further experimental data are required to enable a comparison with bedform development in open-channel flows and develop a new phase diagram applicable to bedform development beneath gravity currents.

This study conducted laboratory experiments to fill gaps in the existing experimental data to develop new bedform phase diagrams for saline-gravity

currents with dimensionless parameters as axes to explore relationships among bedform phases, sediment particles, and flow conditions. The effect of the vertical flow structure in saline-gravity currents was investigated using parameters that represent the whole layer and the lower layer in different bedform phase diagrams. Finally, discriminant analysis was performed to evaluate the similarity between bedform phase regimes in saline-gravity currents compared with open-channel flows. The outcome was used to establish improved bedform phase diagrams for saline-gravity currents, that significantly enhance our ability to reconstruct palaeo-flow conditions from sedimentary structures of turbidites (Ohata *et al.*, 2017) as well as understanding dynamics of gravity currents.

#### METHODS

#### **Experimental setup**

Experiments were carried out at the Total Environmental Simulator of the University of Hull, United Kingdom. The Total Environmental Simulator is 10 m long, 6 m wide and 1.8 m deep tank. An experimental flume (10 m long, 0.1 m wide, and 0.6 m deep) was submerged in the tank with a constant bottom slope (Fig. 2). A 15 cm thick sediment bed was placed in the flume. Sediment particles used to build the bed were urea-based plastic media with a specific gravity of 1.5. Two grades of plastic sediment were used, with a narrow grain-size distribution (Dorrell *et al.*, 2018), thus characterized by their respective median diameters  $D_{50}$  of 253.6 and 428.3 µm (Fig. 3; Table 1). A hopper filled with the sediments was located at the upstream end to replenish the bed. Salt and water were mixed in four mixing tanks using sump pumps before each run. The capacity of each mixing tank was 1 m<sup>3</sup>, and one of the tanks was used to feed the water-

salt mixture into the flume at a constant rate using a metered flow pump. The inlet flow discharge was controlled, via an inverter, by an in-house MATLAB code with a computer connected to the pump. Other mixing tanks were used to keep a constant head in the main mixing tank. A flow diffuser consisting of coarse gravel in a wire mesh was located at the upstream end to ensure the water-salt mixture was injected uniformly.

Velocity profiles were obtained at 7.6 m and 8.2 m from the inlet using Nortek Vectrino Profiler Acoustic Doppler Velocimeters (ADV; Nortek Group, Rud, Norway). In several runs, the ADVs were moved manually in the vertical direction to adjust the measurement height relative to the bed. See more details about the velocity measurements in the Data Processing section. Density profiles were collected using a peristaltic pump and a siphon system at 6.3 m from the inlet. The siphon system had 24 tubes, and the intervals of tubes were 1 cm (from the lowest to 12th tubes), 1.5 cm (from the 12th to the 18th tubes), 2 cm (from the 18th to the 21st tubes), and 4 cm (from the 21st to the top tubes). The syphon system was introduced into the flume for 2 to 3 minutes at intervals of 5 minutes. For each run, three to six sets of flow samples were collected. The saline density of collected samples was measured using density meters (Anton Paar, Austria). Videos of experiments were taken from the side walls using four underwater GoPro Hero 4 (GoPro, Inc., San Mateo, CA, USA) cameras positioned at different points along the flume. Red dye was introduced to the inflow in order to visualize the current.

A total of six runs was conducted. The experimental conditions are summarized in Table 2. The parameters that were changed among the experimental runs were the inlet discharge  $Q_{in}$  (1.5, 2.0 or 3.0 L/s), the bottom slope *S* (0.012 or 0.052, corresponding to 0.7 or 3.0 degrees), the median diameter of plastic sediment  $D_{50}$  (253.6 or 428.3 µm). The

temperature of ambient water and water-saline mixture ranged from 15 to 17 degrees Celsius. The saline density of mixing tanks was from 1060 to 1070 kg/m<sup>3</sup>. The sediment bed was manually flattened before each run.

#### **Data Processing**

#### Newly obtained experimental data

Hydraulic parameters characterizing saline-gravity currents were calculated based on velocity and density profiles (Fig. 4). Seven parameters were used to calculate dimensionless parameters for phase diagrams: the layer-averaged flow velocity U, the maximum velocity  $U_m$ , the bed-related shear velocity  $u_*$  (hereafter bed-related is omitted for simplicity), the layer-averaged flow thickness H, the distance above the bed  $H_m$  showing the maximum velocity, the whole-layer-averaged density of saline-gravity currents  $\rho_{g}$ , and the lower-layer-averaged density of saline-gravity currents  $\rho_{gL}$ . Figures 1B and 1C illustrate the typical velocity and density profiles associated with these hydraulic parameters.

To obtain velocity and density profiles characterizing experimental runs, timeaveraged values were extracted from time series of measured values. The velocity profiles were measured at the condition where the bedform was fully developed in the case of ripples and dunes, following the procedure used in previous studies (Sequeiros *et al.*, 2010a; Fedele *et al.*, 2016). The bed condition was assumed to be fully hydraulically rough. These were necessary to compare our results with existing datasets. The bed parallel component of measured velocities was extracted and averaged over a period of 200 s where the syphon array was not placed into the flume. However, in the case where the antidune developed through an experimental run, the velocities were averaged at the time series before the bedforms appeared, and the initial distance from the bed to the ADV probes was used to set the local height of measured velocity. This was because the suspended load was too dense at the condition where antidunes were fully developed. The densities were averaged over all sets of flow samples except for the first set of samples. The height of the siphon rakes was measured visually using the video recordings.

The whole-layer-averaged velocity *U*, flow thickness *H* and density  $\rho_g$  were defined by integration of profiles of parameters as follows (Ellison and Turner, 1959):

$$UH = \int_0^\infty u \, dz \tag{1}$$

$$U^2 H = \int_0^\infty u^2 dz \tag{2}$$

$$\rho_{\rm g}H = \int_0^\infty \rho_{\rm g,i} \, dz \tag{3}$$

where *U* denotes the local flow velocity, and  $\rho_{g,i}$  denotes the local density of flows. In this study, the whole-layer-averaged velocity *U* and flow thickness *H* were estimated using the empirical relationships (e.g. Sequeiros *et al.*, 2010b) because the full profiles of velocity were not measured. The whole-layer averaged density was computed as follows:

$$\rho_{\rm g} = \frac{\int_{z_{\rm min}}^{H} \rho_{\rm g,i} \, dz}{H - z_{\rm min}} \tag{4}$$

where  $z_{\min}$  is the lowest height measured by the syphon system.

The layer-averaged flow thickness *H* was estimated from the height of interface  $H_a$  between gravity current and ambient water. Sequeiros *et al.* (2010b) implied that the interface height defined by both the density and the velocity profiles of flows is proportional to the layer-averaged flow thickness of turbidity currents. Based on the empirical relationships

proposed by Sequeiros *et al.* (2010b), this study estimated the layer-averaged flow thickness H by  $H = H_a/1.4$  where the height  $H_a$  was obtained from the density profiles (Fig. 4B). The height of interface  $H_a$  was set to the location where the density excess was zero.

The shear velocity  $u_*$  was calculated using the logarithmic law (e.g. Keulegan, 1938) given by:

$$\frac{u}{u_*} = \frac{1}{\kappa} \ln\left(\frac{z}{z_0}\right) \tag{5}$$

where  $\kappa$  is the von Kármán constant (= 0.4) and  $z_0$  is the bed roughness height. Equation 5 is rewritten to the semi-logarithmic form:

$$u = \frac{u_*}{\kappa} \ln z - \frac{u_*}{\kappa} \ln z_0 \tag{6}$$

By fitting the local velocity and its height with the least square regression method, the shear velocity  $u_{*}$  and the bed roughness height  $z_{0}$  can be computed (Fig. 5). Flow variation over the distance between the two spatially offset ADV (Figs 9–13) yields variation in measurements of flow velocity (Fig. 5). It should be noted that each ADV can measure the flow velocity only in a vertical range of 3 cm. Therefore, the ADV that covers the near-bed region was chosen, and the shear velocity was calculated from the velocity profile in the lowermost region of the experimental flow below the height of velocity maximum. From Equation 6, estimates for shear velocity were made in the near-bed region, 0.01 < z < 0.02 m, to avoid the near-bed viscous sublayer and the horizon near the maximum velocity where the velocity profile deviates from the logarithmic form. In cases where both ADVs partially cover this analysis range, the ADV that has longer interval in the domain ranging 0.01 < z < 0.02 m was employed to provide an estimate for flow shear velocity.

To estimate bulk flow parameters, data collected has to be extrapolated: the layeraveraged flow velocity U, the maximum velocity  $U_m$ , and the height of velocity maximum  $H_{\rm m}$  were estimated using the following equations proposed by previous studies (e.g. Sequeiros *et al.*, 2010b):

$$U_{\rm m} = C z_{\rm m} u_* \tag{7}$$

$$Cz_{\rm m} = \frac{1}{\kappa} \ln\left(\frac{30H_{\rm m}}{k_{\rm s}}\right) \tag{8}$$

$$H_{\rm m} = H(0.8 - 0.27 {\rm Fr}_{\rm d}) \tag{9}$$

with:

$$Fr_{d} = \frac{U}{\sqrt{\frac{\Delta\rho}{\rho_{a}}gH}}$$
(10)

$$U = \frac{U_{\rm m}}{1.3} \tag{11}$$

with the density data from density profile and the estimated H, the simplex search method was used to solve these Eqs 7 to 11.

Here,  $Cz_m$  denotes a Chezy friction coefficient based on the maximum velocity  $U_m$  and  $k_s$  is the grain roughness height estimated as  $k_s = 30z_0$ . The parameter  $Fr_d$  is the densimetric Froude number where  $\Delta \rho (= \rho_g - \rho_a)$  denotes the density difference between the current and the ambient water,  $\rho_a$  denotes the density of ambient water, and g is the gravitational acceleration. Equations 7 and 8 were proposed by Sequeiros *et al.* (2010b) and Equation 9 was derived by Abad *et al.* (2011), for saline driven gravity currents. Equation 11 is the empirical relationship by Altinakar *et al.* (1996).

The lower-layer-averaged density  $\rho_{gL}$  was calculated by integration of density profile as follows:

$$\rho_{\rm gL} = \frac{\int_{z_{\rm min}}^{H_{\rm m}} \rho_{\rm g\,i} \, dz}{H_{\rm m} - z_{\rm min}} \tag{12}$$

#### **Existing data of gravity currents**

In addition to the experimental data of this study, the hydraulic parameters were calculated using the data reported by Koller (2016) and Fedele *et al.* (2016). Koller (2016) and Fedele *et al.* (2016) reported the layer-averaged flow velocity U, the flow thickness H, and density  $\rho_{\rm g}$  calculated using the moment equations of Ellison and Turner (1959). Koller (2016) also provided the maximum velocity  $U_{\rm m}$ , the height  $H_{\rm mv}$  the shear velocity  $u_*$ , and the vertical profiles of velocity and density. In contrast, these parameters representing hydraulic conditions of the lower layer were not addressed in the dataset of Fedele *et al.* (2016). Therefore, hydraulic parameters of the lower layer for Fedele's experimental runs were needed to be estimated using empirical relationships.

**Koller (2016)** The flow parameters provided by Koller (2016) are the layer-averaged flow velocity U, the flow thickness H, the maximum velocity  $U_{\rm m}$ , the height  $H_{\rm m}$ , and the shear velocity  $u_*$ .

The parameters *U*, *H*, and layer-averaged density  $\rho_{\rm g}$  were computed using the moment equations of Ellison and Turner (1959) in Koller (2016). Although Koller (2016) reported the layer-averaged density  $\rho_{\rm g}$ ,  $\rho_{\rm g}$  and  $\rho_{\rm gL}$  were calculated based on the density profiles of Koller's experiments and used to obtain the dimensionless numbers.

Abad et al. (2011) proposed the vertical profile of excess density as follows:

$$\zeta_{\rm c} = \begin{cases} 1 & ({\rm Fr}_{\rm d} < 0.38) \\ 2.59 \exp(-2.5 {\rm Fr}_{\rm d}) & ({\rm Fr}_{\rm d} \ge 0.38) \end{cases}$$
(13)

$$f_{\delta c} = \frac{2}{1 + \zeta_c} \tag{14}$$

$$f_{\delta} = \begin{cases} f_{\delta c} \frac{1-\zeta}{1-\zeta_{c}} & (\zeta_{c} < \zeta < 1) \\ f_{\delta c} & (\zeta \le \zeta_{c}) \end{cases}$$
(15)

where  $\zeta$  is the elevation normalized by *H* and  $\zeta_c$  is the elevation below which the density is approximated to constant. The parameter  $f_{\delta}$  is the normalized vertical variation of excess density and  $f_{\delta c}$  is the value of excess density approximated to constant near the bed. The normalized excess density  $f_{\delta L}$  in the lower layer was obtained by integration of Eq. 15.

The present study has tested the relationships for  $H_{\rm m}$  and  $\rho_{\rm gL}$  using Koller's experimental data (Figs 6 and 7). The comparison between the observed  $H_{\rm m}$  and Eq. 9 shows that the data of Koller (2016) scattered within the data of Abad *et al.* (2011) (Fig. 6). Figure 7 shows the comparison of the submerged specific density in the near bed region  $R_{\rm b}$  based on the density calculated from the vertical profile and estimated density using Eqs 9 and 13 to 15. The submerged specific density in the near bed region  $R_{\rm b}$  was computed as follows:

$$R_{\rm b} = \frac{\rho_{\rm s} - \rho_{\rm gL}}{\rho_{\rm gL}} \tag{16}$$

Although the equations by Abad *et al.* (2011) slightly underestimated  $R_b$ , the data of Koller (2016) plotted along the identity line (Fig. 7). Figures 6 and 7 show that the empirical relationships can be used to estimate the hydraulic parameters; therefore, the above equations were used to estimate the parameters for the data of Fedele *et al.* (2016).

Fedele *et al.* (2016) reported the layer-averaged flow velocity *U*, the flow thickness *H*, and density  $\rho_{\rm g}$  calculated using the moment equations of Ellison and Turner (1959). Further, Fedele *et al.* (2016) provided a Shields diagram using some data where the reliable estimates of shear velocity were obtained.

The maximum velocity  $U_{\rm m}$ , the height  $H_{\rm m}$ , and the density of lower layer  $\rho_{\rm gL}$  are not reported in the dataset of Fedele *et al.* (2016). Therefore,  $U_{\rm m}$ ,  $H_{\rm m}$  and  $\rho_{\rm gL}$  of their experimental runs were estimated using Equations 11, 9 and 13 to 15, respectively. Shields numbers  $\tau_*$  were read from the Shields diagram proposed by Fedele *et al.* (2016).

#### Existing data of open-channel flows

Dimensional parameters for open-channel flows were compiled from the literature. In the calculation of the shear velocity  $v_*$  for laboratory data, the side-wall effect was removed using the method of Chiew and Parker (1994) [see Ohata *et al.* (2017) for details], and then the bed component of shear velocity was computed. For the field data, the shear velocity was computed by  $v_* = \sqrt{ghS}$ . Here, *h* denotes the flow depth of open-channel flows.

#### **Governing Parameters**

Bedform phases were expressed in the space of dimensionless parameters that reflect the properties of flows and sediment particles (van den Berg and van Gelder, 1993; Ohata *et al.*, 2017). First, the hydraulic conditions of saline-gravity currents were examined with the sediment diameter and the mobility of bed particles. The following dimensionless parameters were employed to represent hydraulic conditions and sediment properties: the particle Reynolds number  $\text{Re}_{p}$ , Shields number  $\tau_*$  and Froude number Fr. These parameters correspond to  $\text{Re}_{pg'}$ ,  $\tau_{*g}$  and  $\text{Fr}_d$  in the case of salinegravity currents.

The stability conditions of the gravity current bedforms were also investigated using the dimensionless flow velocity  $V^0$  and flow thickness  $h^0$  proposed by Southard and Boguchwal (1990). To examine the effect of the vertical structure of saline-gravity currents, the dimensionless flow velocity and thickness that represent the whole layer  $(U^0, H^0)$  and lower layer  $(U^0_m, H^0_m)$  were employed.

## **Open-channel flows**

The particle Reynolds number Re<sub>p</sub> (Vanoni, 1974) is defined as:

$$Re_{p} = \frac{\sqrt{RgD_{50}}D_{50}}{\nu}$$
(17)

Here,  $\nu$  denotes the kinematic viscosity of the fluid and R is the submerged specific density of the sediment for open-channel flows given as:

$$R = \frac{\rho_{\rm s} - \rho_{\rm f}}{\rho_{\rm f}} \tag{18}$$

where  $\rho_{\rm s}$  and  $\rho_{\rm f}$  denote the densities of the sediment and the water.

The kinematic viscosity  $\nu$  was assumed to be a function of temperature according to the relationship for clear water (van den Berg and van Gelder, 1993):

$$\nu = [1.14 - 0.031(T - 15) + 0.00068(T - 15)^2]10^{-6}$$
<sup>(19)</sup>

where *T* represents the water temperature in degrees Celsius. A value of  $20^{\circ}$ C was assumed for data where *T* was not reported.

Shields number  $\tau_*$  and Froude number are defined as, respectively:

$$\tau_* = \frac{{v_*}^2}{RgD_{50}}$$
(20)

$$Fr = \frac{V}{\sqrt{gh}}$$
(21)

where *V* is the mean flow velocity. Flows with a Froude number larger than unity are referred to as Fr-supercritical flows, while flows with a Fr < 1 are referred to as Fr-subcritical flows.

Dimensionless flow velocity  $V^0$  and flow thickness  $h^0$  for open-channel flows are obtained as (Southard and Boguchwal, 1990):

$$V^{0} = V \left(\frac{1}{\nu Rg}\right)^{\frac{1}{3}}$$
(22)

$$h^0 = h \left(\frac{Rg}{\nu^2}\right)^{\frac{1}{3}} \tag{23}$$

#### Saline-gravity currents

The particle Reynolds number for saline-gravity currents Re<sub>pg</sub> is defined as (Sequeiros *et al.,* 2010a):

$$\operatorname{Re}_{\rm pg} = \frac{\sqrt{R_{\rm b}gD_{50}}D_{50}}{\nu}$$
(24)

Here, the submerged specific density in the near bed region  $R_{\rm b}$  is given as:

$$R_{\rm b} = \frac{\rho_{\rm s} - \rho_{\rm b}}{\rho_{\rm b}} \tag{25}$$

where  $\rho_{\rm b}$  denotes the near-bed density of saline-gravity currents (Sequeiros *et al.,* 2010a). In this study,  $\rho_{\rm gL}$  was employed as the near-bed density of the fluid. Therefore,  $R_{\rm b}$  was computed as follows:

$$R_{\rm b} = \frac{\rho_{\rm s} - \rho_{\rm gL}}{\rho_{\rm gL}} \tag{26}$$

The kinematic viscosity  $\nu$  was calculated using Equation 19, and  $\nu$  of this study was set to  $1.08 \times 10^{-6} \text{ m}^2\text{s}^1$  ( $T = 17^{\circ}\text{C}$ ). A value of  $20^{\circ}\text{C}$  was assumed for published data where T was not reported.

Shields number  $\tau_{*g}$  is defined as (Sequeiros *et al.*, 2010a):

$$\tau_{*g} = \frac{{u_*}^2}{R_{\rm b}gD_{50}} \tag{27}$$

The densimetric Froude number  $Fr_d$  is defined by Equation 10. It is suggested that the critical value of  $Fr_d$  can be non-unity because of the nonuniform vertical velocity and density profiles (Waltham, 2004; Huang *et al.*, 2009; Dorrell *et al.*, 2016; Wu *et al.*, 2019).

Dimensionless flow velocity  $U^0$  and flow thickness  $H^0$  for saline-gravity currents were obtained as:

$$U^{0} = U\left(\frac{1}{\nu R_{g}g}\right)^{\frac{1}{3}}$$
(28)

$$H^{0} = H \left(\frac{R_{\rm g}g}{\nu^{2}}\right)^{\frac{1}{3}}$$
(29)

where the submerged specific density for saline-gravity currents  $R_g$  was computed as  $R_g = (\rho_s - \rho_g)/\rho_g$ . Dimensionless maximum flow velocity  $U_m^0$  and flow thickness of lower layer  $H_m^0$  of saline-gravity currents were given as:

$$U_{\rm m}^0 = U_{\rm m} \left(\frac{1}{\nu R_{\rm b} g}\right)^{\frac{1}{3}}$$
(30)

$$H_{\rm m}^{0} = H_{\rm m} \left(\frac{R_{\rm b}g}{\nu^2}\right)^{\frac{1}{3}}$$
(31)

#### **Bedform classification**

Compiled data of open-channel flow bedforms were classified into five types: ripples, ripples/dunes, dunes, upper-plane beds, antidunes. Antidunes were assigned to the same class as in the original references. Upper-plane beds were assigned for the data of plane beds where Shields number exceeds the threshold of suspension (Ohata *et al.*, 2022). Ripples, ripples/dunes, dunes were classified using the criteria proposed in Lapotre *et al.* (2017).

Lapotre *et al.* (2017) developed a new scaling relation for ripple wavelength that allows us to distinguish ripples and dunes as follows:

$$\lambda^* = 2504\chi^{\frac{1}{3}} \tag{32}$$

where:

$$\lambda^* = \frac{\lambda v_*}{\nu} \tag{33}$$

$$\chi = \operatorname{Re}_* \sqrt{\tau_*} \tag{34}$$

Here,  $\chi$  is Yalin number and Re<sub>\*</sub> is the shear Reynolds number, defined as:

$$Re_{*} = \frac{v_{*}D_{50}}{v} = \frac{v_{*}}{\sqrt{RgD_{50}}}Re_{p}$$
(35)

The shear Reynolds number  $Re_*$  express the relation of the acting forces to the bed particles (Shields, 1936).

Based on Eqs 20 and 35, Eq. 34 is rearranged as:

$$\chi = \operatorname{Re}_* \sqrt{\tau_*} = \operatorname{Re}_p \tau_* \tag{36}$$

Lapotre *et al.* (2017) proposed that the data follow Eq. 32 are interpreted as ripples. The data with  $\chi < 4$  follow Eq. 32, whereas the data with  $\chi < 9$  have much larger  $\lambda^*$  than that predicted by Eq. 32. Therefore, bedwaves with  $\chi < 4$ ,  $4 \le \chi \le 9$ , and  $9 < \chi$  can be interpreted as ripples, transitional bedforms and dunes, respectively (Lapotre *et al.*, 2017).

The bedforms observed in the experiments of this study were classified on the basis of the length, shape, and migration direction of the bed waves. The data for ripples and dunes under saline-gravity currents by Koller (2016) were reinterpreted using Eq. 32 (Fig. 8). Figure 8 shows that the Yalin number of 9 seems to correspond to the boundary between ripples and dunes under saline-gravity currents. However, all data plotted along Eq. 32, thus the ripple and dune data of Koller (2016) were classified as ripples. Fedele *et al.* (2016) do not report the wavelength of bedforms. Therefore, compiled data of gravity-current bedforms by Fedele *et al.* (2016) were assigned to the same class as in Fedele *et al.* (2016).

#### **Discriminant Analysis**

The discriminant analysis was applied to identify the stability conditions of openchannel flow bedforms in the  $V^0-h^0$  space. The discriminant analysis is a classical statistical method that has been used for classification problems in various research areas (e.g. AbuZeina and Al-Anzi, 2018; Mahmoudi and Duman, 2015; Zou *et al.*, 2019). Recently, Ohata *et al.* (2017) employed discriminant analysis to classify bedform phase regimes. The discriminant analysis determines a function to categorize a set of parameters on the basis of given categorized sets of variables (Fukunaga, 1990). Here, the classification method using the Mahalanobis distance (De Maesschalck *et al.*, 2000) was employed to obtain the boundaries of bedform phase regimes. The Mahalanobis distance measures the distance in parametric space between a data point and a categorized group of data points. The mathematical definition of the Mahalanobis distance is as follows:

$$d_{\mathrm{M}}(\mathbf{x}) = \sqrt{(\mathbf{x} - \boldsymbol{\mu})^{\mathrm{T}} \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})}$$
(37)

Here,  $d_{\rm M}$  denotes the Mahalanobis distance, **x** is an observation vector,  $\mu$  is the mean vector of a group, a superscript *T* denotes the transpose of a vector, and  $\Sigma$  denotes the covariance matrix. A data point can be assigned to a categorized group that shows the shortest Mahalanobis distance among all groups. Thus, if the Mahalanobis distance of a data point of a type of bedforms (for example, ripples) shows the shortest distance to a group of other types of bedforms (for example, dunes), the data point will be regarded as misclassified data. The transitional bedforms between ripples and dunes were considered to be accurately classified when the Mahalanobis distance was shortest to ripples or dunes.

The discriminant analysis allows us to evaluate the accordance of the observed data with the bedform phase regimes of open-channel flows obtained by the discriminant analysis. In the discriminant analysis, the inaccuracy of the classification model fitted to the original data points is expressed as an error rate  $r_e$  (Efron, 1986). This study utilized the apparent error rate, that is the observed inaccuracy of the model, for observational data of open-channel flows vs. saline-gravity currents.

#### RESULTS

#### Bedforms

Two kinds of bedforms were observed in the present experiments: ripples and antidunes. Each of the different bedforms observed in the experimental runs is described below. In runs 6, 7, 9 and 10, bedforms were interpreted as ripples (Figs 9 and 10). Equation 32 was used to interpret these bedforms (Fig. 11) in this study. Although the bedforms observed in this study can be interpreted as ripples (the data with  $\chi < 4$ ) or dunes (the data with  $\chi > 4$ ), the wavelength is relatively smaller than bedforms under open-channel flows and the data plotted along Eq. 32. Therefore, the bedforms observed in runs 6, 7, 9 and 10 were classified as ripples in this study.

The bed configurations in runs 3 and 5 were recognized as antidunes. Figure 12 shows the temporal development of bedforms in Run 3. The bedforms initiated as configurations with long-wavelength (h = 60-110 cm) and symmetrical profiles, then slowly propagated downstream or became stationary. At the latter stage of Run 3, short-length waves (h = 20-30 cm) reworked or superimposed on the large-scale waves. In Run 5, the bedforms observed at the upstream end of the flume had steep stoss and gentle lee slopes, and migrated in an upstream-direction slowly (Fig. 13). At the downstream end, the bedforms were symmetrical and remained stationary. The wavelength and wave height of bedforms in Run 5 were larger than that of Run 3 (Figs 12 and 13). From the profiles and wavelength, the bedforms in runs 3 and 5 were classified as antidunes.

#### **Bedform Phase diagram**

The experimental data reported in this study and previous studies (Fedele et al., 2016;

Koller, 2016) were compared with the existing observational data of open-channel flows. The bedform phase regimes were described in the following two-dimensional spaces: (i) Shields diagram ( $\text{Re}_{p}-\tau_{*}$  and  $\text{Re}_{pg}-\tau_{*g}$ ; Fig. 14); (ii) Froude diagram ( $\text{Re}_{p}$ -Fr and  $\text{Re}_{pg}$ -Fr<sub>d</sub>; Fig. 15); (iii) Velocity-Depth diagram ( $V^{0}-h^{0}$ ,  $U^{0}-H^{0}$ , and  $U_{m}^{0}-H_{m}^{0}$ ; Fig. 16).

#### Shields diagram

The flume data were plotted onto Shields diagram where  $\text{Re}_{p}$  ( $\text{Re}_{pg}$ ) and  $\tau_{*}$  ( $\tau_{*g}$ ) are shown on the vertical and the horizontal axis, respectively, to investigate relationships between particle diameter and shear stresses (Fig. 14). Figure 14 shows that stability fields of bedforms produced by saline-gravity currents do not deviate largely from those of open-channel flows in the Shields diagram. The dune data of Fedele *et al.* (2016) plot above the criteria of the dune stability field proposed by Lapotre *et al.* (2017), while the stability conditions of ripples reported by Koller (2016) were mostly plotted below the criteria. However, the stability fields of antidunes and plane beds cannot be clearly distinguished in Fig. 12 for both saline-gravity currents and open-channel flows because the stability fields of these two bedforms show an overlap, although antidunes have relatively higher Shields number than upper plane beds.

#### **Froude diagram**

Figure 15 shows a plot of Fr versus  $\text{Re}_{p}$  for the data of open-channel flows and  $\text{Fr}_{d}$  versus  $\text{Re}_{pg}$  for the data of saline-gravity currents. The open-channel flow data demonstrates that most of the bedforms in the lower flow regime (lower-plane bed, ripples, and dunes) plot in a region ranging Fr < 0.8, and some dune data points with  $D_{50} > 0.8$  mm have larger Fr than unity. In contrast, the upper-flow-regime bedforms

(upper-plane bed and antidunes) tend to have high Fr ranging from 0.5 to 4.3, and most of the data plot in 0.5 < Fr < 2. However, the data of saline-gravity currents shows much higher Fr<sub>d</sub> than Fr of open-channel flows. The lower-flow-regime bedforms of saline-gravity currents plot in 0.5 < Fr<sub>d</sub> < 2.8, and the upper-flow-regime bedforms plot in 1.2 < Fr<sub>d</sub> < 2.3.

#### Velocity-Depth diagrams

The velocity-depth diagrams of bedforms were described in the space of: (i)  $V^0$  versus  $h^0$  for open-channel flows and  $U^0$  versus  $H^0$  for saline-gravity currents (the whole layer velocity-depth diagram; Figs 16A and 17A); and (ii)  $V^0$  versus  $h^0$  for open-channel flows and  $U_m^0$  versus  $H_m^0$  for saline-gravity currents (the lower layer velocity-depth diagram; Figs 16B and 17B). Since the particle diameter of gravity-current bedforms ranges  $2 < \text{Re}_p < 45$ , the data of open-channel flows with  $2 < \text{Re}_p < 45$  were used for both the velocity-depth diagrams. In addition, velocity-depth diagrams of bedforms were described for finer sediment ( $\text{Re}_p, \text{Re}_{pg} \le 11.37$ ; Fig. 16) and coarser sediment  $\text{Re}_p$ ,  $\text{Re}_{pg} > 11.37$ ; Fig. 16). The particle Reynolds number  $\text{Re}_p = 11.37$  corresponds to the sediment with  $D_{50} = 0.2$  mm and R = 1.65.

Figures 16 and 17 shows that the sequence of open-channel flow bedforms from ripples to dunes, upper-plane bed, and antidune as  $V^0$  increases. In addition, most dune data plotted on the diagram for coarse sediment (Fig. 17). The sequence of gravity-current bedforms from ripples to dunes and antidunes were also observed, although the data from Fedele *et al.* (2016) shows the overlapping of the data points. Also, the data from Fedele *et al.* (2016) fall in a region where the data of open-channel flows are sparse (Figs 16 and 17).

#### Discriminant analysis

Applying discriminant analysis, the stability conditions of bedforms were obtained as illustrated in Figs 18 and 19. The total apparent error rates for open-channel flows are 0.14% and 0.12% for fine and coarse sediment, respectively (Table 3). The apparent error rates  $r_{\rm e}$  of each bedform are summarized in Table 3. Figures 18 and 19 show the velocity-depth diagrams with the bedform phase regimes of open channel flows obtained by discriminant analysis. The experimental data of saline-gravity currents were plotted using  $U^0$  versus  $H^0$  (Figs 18A and 19A) and  $U_{\rm m}^0$  versus  $H_{\rm m}^0$  (Figs 18B and 19B).

As a result of discriminant analysis of experimental data based on the wholelayer averaged values, almost all data of saline-gravity currents fall in the ripple and ripple/dune regimes of open-channel flow (Figs 18A and 19A). Thus, all ripple data are correctly classified as is obvious ( $r_e = 0$ ) (Tables 4 and 5). Most data of dunes and antidunes as well as plane beds, however, are misclassified to the fields of different bedforms.

In contrast, Figs 18B and 19B and Tables 4 and 5 demonstrate that the gravitycurrent bedforms compare more favourably to open-channel flow by using the lowerlayer values  $U_m^0$  and  $H_m^0$ . The error rates of dunes and upper-plane beds significantly decrease from 0.5–1.0 to 0–0.38, respectively (Tables 4 and 5). Even though the error rate of antidunes does not improve well compared to the whole layer velocity-depth diagram, the data of antidunes plot closer to the antidune regime of open-channel flows in the lower layer velocity-depth diagram. In the case of fine sediment, the total error rate of the lower-layer diagram ( $r_e = 0.4$ ) is almost the same as that of the whole-layer diagram  $(r_{\rm e} = 0.41)$ . In addition,  $r_{\rm e}$  of ripples increases from 0 to 0.16 in the diagram for fine sediment (Table 4). These are because almost all data plot in ripple regime and therefore the error rate of ripple formed by turbidity currents is 0 in the whole layer velocity-depth diagram. In contrast, in the case of coarse sediment, the total error rate of the lower-layer diagram improved from 0.76 to 0.24 compared to the whole-layer diagram.

#### DISCUSSION

#### Comparison of phase regimes with open-channel flows

This study suggests that the parameters characterizing the lower layer of saline-gravity currents can be used to better understand the relationships between hydraulic conditions and gravity current bedforms, as shown in the lower layer velocity-depth diagram (Figs 18B and 19B). The agreement of phase regimes was found by discriminant analysis using Mahalanobis distances (Tables 4 and 5). Although the whole-layer-averaged parameters have been used to represent the hydraulic conditions of saline-gravity currents (e.g. Parker et al., 1986), the velocity-depth diagram using the whole layer averagedparameters for saline-gravity currents do not coincide with that of open-channel flows (Figs 18A and 19A). The velocity-depth diagram using the whole layer-averaged parameters (Figs 18A and 19A) indicates that the bedform phase diagrams for openchannel flows cannot be applied to gravity current bedforms. The velocity-depth diagram for open-channel flows overestimates the layer-averaged velocity of salinegravity currents and mispredicts that ripples generally appear in laboratory-scale salinegravity currents (Figs 18A and 19A, Tables 4 and 5). Koller (2016) and Koller *et al.* (2017) also compared their experimental data with existing bedform phase diagrams by Simons and Richardson (1966) and Southard and Boguchwal (1990) that were described in parameter spaces using layer-averaged parameters. As a result of the comparison, the data of Koller (2016) and Koller *et al.* (2017) showed disagreements with these phase diagrams. Koller *et al.* (2017) argued that the disagreement stemmed from the difference in the vertical flow structure and bed materials (plastic or siliciclastic particles), although they did not address the role of the lower layer of saline-gravity currents in producing bedforms.

Also, the difference regarding ambient fluids between open-channel flows and saline-gravity currents results in the deviation of the formation condition in the Froude diagram (Fig. 15). The densimetric Froude number of saline-gravity currents is higher than the Froude number of open-channel flows, whereas dunes, upper-plane beds, and antidunes appear in saline-gravity currents at smaller velocities than in open-channel flows, as shown in the whole layer velocity-depth diagram (Figs 18A and 19A). The discrepancy of phase regimes in the Froude diagram was caused by the reduced gravity effect (Fedele *et al.*, 2016). The reduced gravity ( $\Delta \rho / \rho$ )*g* takes a much smaller value than the gravity acceleration *g* because the density of the ambient water is not negligible with respect to that of saline-gravity currents. Therefore, the densimetric Froude number of saline-gravity currents cannot be estimated using the Fr diagram for open-channel flows. However, the densimetric-Froude diagram of this study that is based only on the data pertaining to gravity currents, as shown previously by Fedele *et al.* (2016).

#### **Relation between consistency in bedform phase diagrams and flow dynamics**

Inconsistency of bedform phase diagrams between open-channel flows and saline-

gravity currents suggests that vertical flow structure of saline-gravity currents is the key factor in determining the flow dynamics for generating bedforms. The velocity-depth diagram for the lower layer (Figs 18B and 19B) indicates that the characteristic length of saline-gravity currents with respect to bedform development is represented by the height showing the maximum velocity, whereas that of open-channel flows is the flow depth defined as the distance from the bed to the free surface. From the accordance of the bedform phase regimes in Figs 18B and 19B, it is inferred that the layer interface where the maximum velocity of saline-gravity currents is attained plays a role like the free surface of open-channel flows.

This might be because the lower layer of a gravity flow exhibits a boundary layer-like flow structure that is similar to open-channel flows. Thus, similar evolutionary and hydrodynamic processes occur during the development of bedforms by gravity currents. Morphodynamic feedbacks between gravity currents and bed evolution processes are caused in the conditions of bed shear stress and sediment transport rate analogous to open channel flows. As a result, the maximum velocity might be a better predictor of the bottom-related shear stress of the gravity currents than the layeraveraged velocity that is the result of both bottom and interface friction.

The analogous behaviour of the layer interface with the free surface was observed in the flume experiments (Fedele *et al.*, 2016) and in the field (Dorrell *et al.*, 2019). In openchannel flows, the free-surface undulations show out-of-phase and in-phase relation with dunes and antidunes, respectively. The phase relations between bedforms and the layer interface were also observed in some experimental runs of Fedele *et al.* (2016) [see figs 4A and 8A of Fedele *et al.* (2016)].

Further, Dorrell *et al.* (2019) showed that, for the low- $Fr_d$  saline-gravity currents in

the Black Sea, the layer interface dipped over the crest of the small-amplitude bedforms, i.e. an out-of-phase relation. It was postulated that this internal interface acts like the free surface due to a sharp gradient of potential vorticity. After Dorrell *et al.* (2019), rapid variation in potential vorticity, driven by breaking of gravity waves at critical-layers, inhibits eddy transportation across such a layer, i.e. gravity wave elasticity prevents the mixing of transported materials. This process can be seen to be analogous to Rossby wave forcing of atmospheric jets (Baldwin *et al.*, 2007; Dritschel and McIntyre, 2008; Dorrell *et al.*, 2019). Therefore, the thickness of the lower layer of saline-gravity currents is stabilized, and the layer interface behaves similarly to the free surface over the bedforms.

The phase diagram using the hydraulic parameters not related to the  $H_m$ , shown in Fig. 14, demonstrates that the bedform stability conditions in saline-gravity currents exhibit good agreement with those of open-channel flows in the Shields diagram. Fedele *et al.* (2016) also reported that their experimental data fall in the prediction regimes of ripples and dunes, when comparing Shields numbers. This agreement of phase regimes can be accounted for by the dynamical mechanisms that transport the bed materials in open-channel flows and saline-gravity currents. Shields numbers have been employed to formulate the bed-load transport rate in open-channel flows (e.g. Meyer-Peter and Müller, 1948; Wong and Parker, 2006). For gravity currents, Sequeiros *et al.* (2010b) measured the bed-load transport rate in experimental gravity currents and discovered that the transport rate follows the relationships for open-channel flows proposed by Ashida and Michiue (1972) and Wong and Parker (2006). The accordance of the bed-load transport relations in both flows suggests that open-channel flows and gravity currents interact with the sediment bed through similar dynamical mechanisms

(Sequeiros *et al.*, 2010b). Therefore, the bedform phase diagrams of saline-gravity currents and open-channel flows coincide well in the Shields space (Fig. 14).

Although the analogy between the lower layer of gravity currents and open-channel is also recognized in the velocity profiles (Sequeiros *et al.*, 2010b), the density structures of both currents are different. Air has a small density relative to the water in the case of open-channel flows, whereas the density of the upper layer is not negligible with respect to the lower layer of gravity currents. Also, the gravity currents are vertically stratified with the density, which may have an influence on the flow dynamics Dorrell *et al.* (2014). These hydrodynamic deviations of gravity currents from the open-channel flows are not incorporated in the parametric space of the lower layer velocity-depth diagram. Fedele *et al.* (2016) pointed out that the hydraulic conditions of the lower layer are also significant in considering behaviour of dunes formed by gravity currents. Further observation is required to understand the relationships between the density field of gravity currents and bedforms.

#### CONCLUSIONS

This paper reports new experiments of bedform formation by saline-gravity currents over an erodible sediment bed. Based on these results and a dataset compiled from the literature, the bedform phase diagrams for saline-gravity currents are examined in dimensionless parameter spaces. For the first time it is shown that bedform development by saline-gravity currents can only be assumed to be equivalent to openchannel flows if dimensionless saline-gravity-current parameters are based on the lower layer of the flow (i.e. that part below the velocity maximum). These results imply that the lower layer of the flow is the principal control on saline-gravity-current morphodynamics and hydrodynamics.

The new understanding of morphodynamic and hydrodynamic processes of salinegravity currents demonstrated in the analysis of bedform phase space has significant implications for engineering and field geology. The erosion and scour risk that gravity currents pose to offshore infrastructure engineering should be parameterized in terms of estimates of the lower layer of flows. Moreover, the interpretation of gravity-current deposits using the phase diagram for open-channel flow should only be used with the flow velocity and thickness of the lower layer of gravity currents, not the entire flow as has been previously applied. This latter point is critical for interpreting the sedimentary record and accurately reconstructing palaeoflow regimes to predict sediment transport conditions. Previous work (e.g. Lowe, 1988) interpreting the evolution of submarine fans, the largest sedimentary landforms on our planet, can be erroneous and should be reinterpreted for hydraulic conditions in the lower layer of the depositing gravity currents.

The precise estimation of flow conditions based on sedimentary structures is valuable to verify recently developed methodologies for deep-sea sedimentology. In recent years, direct observations by ADCPs in submarine canyons have provided information on the velocity and thickness of turbidity currents (Paull *et al.*, 2018; Hughes Clarke, 2016). However, turbidity currents that occur more than a few times a year in the modern age do not necessarily exhibit the same characteristics as those that produced ancient turbidites only once every several hundred years (Clare *et al.*, 2014). It is possible that turbidity currents forming actual submarine fans are much larger in scale and less frequent than those observed in the modern submarine canyons. On the other hand, numerical inverse analysis methods have been recently developed to

reconstruct the past hydraulic conditions from the characteristics of turbidites (Lesshafft et al., 2011; Parkinson et al., 2017; Naruse and Nakao, 2021; Cai and Naruse, 2021). Those methodologies potentially estimate the past flow conditions from geological records, but they depend on the accuracy of numerical forward models. For validating those methods at the scale of actual submarine fans, independent methods such as the discriminant analysis of sedimentary structures (Ohata et al., 2017) will become even more significant in future studies.

#### **ACKNOWLEDGEMENTS**

This research was funded by Japan Society for the Promotion of Science (JSPS) Grantin-Aid for JSPS Fellows, JSPS Overseas Challenge Program for young researchers, The Turbidites Research Group, School of Earth and Environment, University of Leeds, UK (Sponsors: AkerBP, BP, ConocoPhillips, Equinor, Eni, Hess, Murphy, OMV, Oxy and Shell), Sediment Dynamics Research Consortium (Sponsors: INPEX, JAPEX, JOGMEC, JX Nippon Oil and Gas Exploration), the Leeds Anniversary Research Scholarship, and the Energy and Environment Institute, University of Hull, UK. We gratefully acknowledge Brendan Murphy at the Total Environment Simulator laboratory, University of Hull, Lee Wilson and the research staff at the University of Hull for their help to set up the experiments. The data that supports the findings of this study are available in Table 2 of this article and were cited from Fedele et al. (2016) and Koller (2016). The data of open-channel flows used for the analysis are summarized in the supplementary tables of this article. Unpublished data used for the analysis were cited from the dataset of Brownlie (2018). The reference refers to the supplementary tables. The authors declare that they have no competing interests. We appreciate the Associate Editor Kyle Straub and two anonymous reviewers for their in-depth comments which greatly improved the manuscript.

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Figure 1 | Typical vertical profiles of (A) velocity of open-channel flows, (B) velocity of gravity currents, and (C) density of gravity currents. (A) V – mean flow velocity, h – flow depth. (B) U – layer-averaged flow velocity,  $U_{\rm m}$  – maximum flow velocity, H – layer-averaged flow thickness,  $H_{\rm m}$  – the height showing the maximum velocity,  $H_{\rm a}$  – the height of interface between gravity current and ambient fluid. (C)  $\rho_{\rm g}$  – mean density of whole layer,  $\rho_{\rm gL}$  – mean density of lower layer,  $\rho_{\rm a}$  – density of ambient water.

Figure 2 | Sketch of the experimental facility.

Figure 3 Grain-size distributions of plastic particles.

Figure 4 | Velocity and density profiles of Run 7.

Figure 5 | Velocity profile of Run 7 and fitted curves to the data within 0.01 m < z < 0.02 m.

Figure 6 | Comparison of  $H_m/H$  of the experimental data by Koller (2016) with the empirical relationship (Equation 9) proposed by Abad *et al.* (2011). The ratio  $H_m/H$  for Fedele *et al.* (2016) was estimated using the Abad's relationship.

Figure 7 | Comparison of  $R_b$  or the data of Koller (2016) between that calculated using the density profile and that estimated using the empirical relationships (Eqs 9 and 13–

15) proposed by Abad et al. (2011). (A) plastic particles. (B) natural sands.

Figure 8 | Comparison between data of gravity-current bedforms by Koller (2016) with the scaling relation (Eq. 32).

Figure 9 | Snapshots of Run 7 ( $Q_{in}$  = 1.5 L/s, S = 0.7 degrees, and  $D_{50}$  = 428.3 µm).

Figure 10 | Snapshots of Run 9 ( $Q_{in}$  = 2 L/s, S = 0.7 degrees, and  $D_{50}$  = 428.3 µm).

Figure 11 | Comparison between data of gravity-current bedforms obtained by this study with the scaling relation (Eq. 32).

Figure 12 | Snapshots of Run 3 ( $Q_{in}$  = 1.5 L/s, S = 3 degrees, and  $D_{50}$  = 428.3 µm).

Figure 13 | Snapshots of Run 5 ( $Q_{in}$  = 2 L/s, S = 3 degrees, and  $D_{50}$  = 253.5 µm).

Figure 14 | Shields number versus particle Reynolds number.

Figure 15 | Froude number versus particle Reynolds number.

Figure 16 | Velocity-depth diagrams of bedforms for finer sediment  $(\text{Re}_{p}, \text{Re}_{pg} \leq 11.37.$  (A) Dimensionless flow thickness  $H^{0}$  versus dimensionless flow velocity  $U^{0}$ . (B) Dimensionless flow thickness of lower layer  $H^{0}_{m}$  versus dimensionless maximum flow velocity  $U^{0}_{m}$ . Figure 17 | Velocity-depth diagrams of bedforms for coarser sediment ( $\text{Re}_{p}, \text{Re}_{pg} > 11.37$ . (A) Dimensionless flow thickness  $H^0$  versus dimensionless flow velocity  $U^0$ . (B) Dimensionless flow thickness of lower layer  $H^0_m$  versus dimensionless maximum flow velocity  $U^0_m$ .

Figure 18 | Comparison of phase spaces of density-current bedforms with phase spaces of open-channel flow bedforms ( $\text{Re}_{p}$ , $\text{Re}_{pg} \leq 11.37$ ) obtained by the discriminant analysis. (A) Dimensionless flow thickness  $H^{0}$  versus dimensionless flow velocity  $U^{0}$ . (B) Dimensionless flow thickness of lower layer  $H^{0}_{m}$  versus dimensionless maximum flow velocity  $U^{0}_{m}$ .

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Figure 19 Comparison of phase spaces of density-current bedforms with phase spaces of open-channel flow bedforms ( $\text{Re}_{p}, \text{Re}_{pg} > 11.37$ ) obtained by the discriminant analysis. (A) Dimensionless flow thickness  $H^{0}$  versus dimensionless flow velocity  $U^{0}$ . (B) Dimensionless flow thickness of lower layer  $H_{m}^{0}$  versus dimensionless maximum flow velocity  $U_{m}^{0}$ .

Sediment	$ ho_{ m s}$	<i>D</i> <sub>10</sub>	D <sub>30</sub>	D <sub>50</sub>	D <sub>70</sub>	D <sub>90</sub>	$\sigma_{ m g}$
	[kg/m <sup>3</sup> ]	[µm]	[µm]	[µm]	[µm]	[µm]	[kg/m <sup>3</sup> ]
1	1500	168.6	214.2	253.6	299.9	382.2	1.375
2	1500	283.6	360.8	428.3	509.5	657.9	1.384

Table 1 | Characteristics of sediments.

Run	S [deg]	D <sub>50</sub> [μm]	Q <sub>in</sub> [L/s]	<i>U</i> [m/s]	<i>Н</i> [m]	<i>u</i> <sub>*</sub> [m/s]	ρ <sub>g</sub> [kg/m³]	U <sub>m</sub> [m/s]	H <sub>m</sub> [m]	ρ <sub>gL</sub> [kg/m³]	Duration [min]	λ [cm]	Bedform
3	3.0	428	1.5	0.4	0.15	0.032	1014.7	0.52	0.044	1031.0	40	60 <	Antidune
5	3.0	253.5	2.0	0.5	0.21	0.035	1019.7	0.64	0.062	1036.7	30	100 <	Antidune
6	0.7	253.5	2.0	0.24	0.18	0.036	1036.7	0.31	0.054	1048.3	30	18.1	Ripple/dune
7	0.7	428	1.5	0.15	0.15	0.019	1027.6	0.19	0.044	1044.2	40	13.8	Ripple
9	0.7	428	2.0	0.19	0.17	0.014	1038	0.24	0.052	1048.5	30	15.9	Ripple/dune
10	0.7	428	3.0	0.19	0.18	0.037	1033.2	0.24	0.053	1042.9	15	14.4	Ripple/dune

Table 2 | Experimental conditions and results.

Padform	Re	, ≤ 11	.37	Re <sub>p</sub> > 11.37			
Deciorin	Ν	n <sub>e</sub>	r <sub>e</sub>	N	$n_{ m e}$	r <sub>e</sub>	
Ripple	67	10	0.15	119	1	0.01	
Ripple/dune	146	12	0.08	396	15	0.04	
Dune	65	3	0.05	377	48	0.13	
Upper plane bed	132	25	0.19	127	42	0.33	
Antidune	67	19	0.28	180	40	0.22	
Total	477	69	0.14	1199	146	0.12	

Table 3 Error rates for open-channel flow bedforms. The parameter *N* denotes the total number of data points,  $n_e$  is the number of misclassified data points and  $r_e$  is the error rate.

Padfarm		Wh	ole layer	Lo	Lower layer		
beatorin	Ν	n <sub>e</sub>	r <sub>e</sub>	$n_{e}$	e r <sub>e</sub>		
Ripple	49	0	0.00	8	0.16		
Dune	13	11	0.85	5	0.38		
Upper plane bed	4	2	0.50	0	0.00		
Antidune	24	24	1.00	23	3 0.96		
Total	90	37	0.41	36	6 0.40		

Table 4 | Error rates for gravity-current bedforms with  $\text{Re}_p \leq 11.37$ . The parameter *N* denotes the total number of data points,  $n_e$  is the number of misclassified data points and  $r_e$  is the error rate.

Rodform		Whol	e layer	Lower layer		
Deutorini	Ν	$n_{ m e}$	r <sub>e</sub>	$n_{ m e}$	r <sub>e</sub>	
Ripple	10	0	0.00	0	0.00	
Dune	25	25	1.00	4	0.16	
Antidune	7	7	1.00	6	0.86	
Total	42	32	0.76	10	0.24	

Table 5 | Error rates for gravity-current bedforms with  $\text{Re}_{p} > 11.37$ . The parameter *N* denotes the total number of data points,  $n_{e}$  is the number of misclassified data points and  $r_{e}$  is the error rate.



Figure 1 | Typical vertical profiles of (A) velocity of open-channel flows, (B) velocity of gravity currents, and (C) density of gravity currents. (A) *V* – mean flow velocity, *h* – flow depth. (B) *U* – layer-averaged flow velocity,  $U_m$  – maximum flow velocity, *H* – layer-averaged flow thickness,  $H_m$  – the height showing the maximum velocity,  $H_a$  – the height of interface between gravity current and ambient fluid. (C)  $\rho_g$  – mean density of whole layer,  $\rho_{gL}$  – mean density of lower layer,  $\rho_a$  – density of ambient water.

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Figure 2 | Sketch of the experimental facility.

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Figure 3 | Grain size distributions of plastic particles.

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Figure 4 | Velocity and density profiles of Run 7.



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m.

Figure 5 | Velocity profile of Run 7 and fitted curves to the data within 0.01 m < z < 0.02



Figure 6 | Comparison of  $H_m/H$  of the experimental data by Koller [2016] with the empirical relationship (Equation 9) proposed by Abad et al. [2011]. The ratio  $H_m/H$  for Fedele et al. [2016] was estimated using the Abad's relationship.



Figure 7 | Comparison of  $R_b$  or the data of Koller [2016] between that calculated using the density profile and that estimated using the empirical relationships (Equations 9 and 13–15) proposed by Abad et al. [2011]. (A) plastic particles. (B) natural sands.



Figure 8 | Comparison between data of gravity-current bedforms by Koller [2016] with the scaling relation (Equation 32).



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Figure 9 | Snapshots of Run 7 ( $Q_{in}$  = 1.5 L/s, S = 0.7 degrees, and  $D_{50}$  = 428.3 µm).



Accer

Figure 10 | Snapshots of Run 9 ( $Q_{in}$  = 2 L/s, S = 0.7 degrees, and  $D_{50}$  = 428.3 µm).



Figure 11 | Comparison between data of gravity-current bedforms obtained by this study with the scaling relation (Equation 32).



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Figure 12 | Snapshots of Run 3 ( $Q_{in}$  = 1.5 L/s, S = 3 degrees, and  $D_{50}$  = 428.3 µm).



Figure 13 | Snapshots of Run 5 ( $Q_{in}$  = 2 L/s, S = 3 degrees, and  $D_{50}$  = 253.5 µm).

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Figure 15 | Froude number versus particle Reynolds number.



Figure 16 | Velocity-depth diagrams of bedforms for finer sediment  $(\text{Re}_p, \text{Re}_{pg} \le 11.37.$  (A) Dimensionless flow thickness  $H^0$  versus dimensionless flow velocity  $U^0$ . (B) Dimensionless flow thickness of lower layer  $H^0_m$  versus dimensionless maximum flow velocity  $U^0_m$ .

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Figure 17 | Velocity-depth diagrams of bedforms for coarser sediment ( $\text{Re}_{p}, \text{Re}_{pg} > 11.37$ . (A) Dimensionless flow thickness  $H^0$  versus dimensionless flow velocity  $U^0$ . (B) Dimensionless flow thickness of lower layer  $H^0_m$  versus dimensionless maximum flow velocity  $U^0_m$ .



Figure 18 | Comparison of phase spaces of density-current bedforms with phase spaces of open-channel flow bedforms ( $\text{Re}_{p}, \text{Re}_{pg} \leq 11.37$ ) obtained by the discriminant analysis. (A) Dimensionless flow thickness  $H^0$  versus dimensionless flow velocity  $U^0$ . (B) Dimensionless flow thickness of lower layer  $H^0_m$  versus dimensionless maximum flow velocity  $U^0_m$ .

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Figure 19 | Comparison of phase spaces of density-current bedforms with phase spaces of open-channel flow bedforms ( $\text{Re}_{p}, \text{Re}_{pg} > 11.37$ ) obtained by the discriminant analysis. (A) Dimensionless flow thickness  $H^0$  versus dimensionless flow velocity  $U^0$ . (B) Dimensionless flow thickness of lower layer  $H^0_m$  versus dimensionless maximum flow velocity  $U^0_m$ .