

1 **Inertial focusing of microparticles, bacteria and blood in**
2 **serpentine glass channels**

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18 **Abstract**

19 Early detection of pathogenic microorganisms is pivotal to diagnosis and prevention
20 of health and safety crises. Standard methods for pathogen detection often rely on
21 lengthy culturing procedures, confirmed by biochemical assays, leading to >24 h for a
22 diagnosis. The main challenge for pathogen detection is their low concentration within
23 complex matrices. Detection of blood-borne pathogens via techniques such as PCR
24 requires an initial positive blood culture and removal of inhibitory blood components,
25 reducing its potential as a diagnostic tool. Amongst different label-free microfluidic
26 techniques, inertial focusing in microscale channels holds great promise for
27 automation, parallelization and passive continuous separation of particles and cells.
28 This work presents inertial microfluidic manipulation of small particles and cells (1-10
29 μm) in curved serpentine glass channels etched at different depths (deep and shallow
30 designs) that can be exploited for (1) bacteria pre-concentration from biological
31 samples and (2) bacteria-blood cell separation. In our shallow device, the ability to
32 focus *Escherichia coli* (*E. coli*) into the channel side streams with high recovery (89%
33 at 2.2x pre-concentration factor) could be applied for bacteria pre-concentration in
34 urine for diagnosis of urinary tract infections. Relying on differential equilibrium
35 positions of red blood cells (RBCs) and *E. coli* inside the deep device, 97% RBCs were
36 depleted from 1:50 diluted blood with 54% *E. coli* recovered at a throughput of 0.7 mL
37 min^{-1} . Parallelization of such devices could process relevant volumes of 7 mL whole
38 blood in 10 min, allowing faster sample preparation for downstream molecular
39 diagnostics of bacteria present in bloodstream.

40 **1 Introduction**

41 Surveillance is the first step in limiting diseases caused by pathogenic
42 microorganisms, and their early detection is crucial for diagnosing and preventing
43 crises related to health, safety and wellbeing [1]. Pathogen detection is often
44 hampered by low concentrations present in complex matrices such as food and body
45 fluids and, as a result, additional pre-concentration and separation steps are usually
46 required prior to analysis [2,3]. For example, in bacteremia, pathogen burden can be
47 as low as 10 – 100 per mL, whilst the host cell background is vastly higher (10^9 blood
48 cells mL^{-1}) [4-6]. Although molecular diagnostics hold the potential to greatly enhance

49 pathogen analysis and identification, standard methods for pathogen detection still rely
50 heavily on traditional lengthy culture techniques to isolate and enumerate viable cells
51 in samples, followed by confirmation using biochemical or serological tests. In blood
52 stream infections, techniques such as PCR, fluorescence *in situ* hybridization and
53 mass spectroscopy require an initial positive blood culture, resulting in 18 to 24 h for
54 a diagnosis [6]. In addition, removal of blood components that interfere with PCR
55 amplification is necessary [7].

56 Conventional methods employing macroscale instruments for label-free cell
57 separation are centrifugation and mechanical filtration [6,8]. Although simple to
58 operate and successful in separating blood components, centrifugation can lead to
59 contamination of sorted levels during extraction and may cause lysing of blood cells
60 and poor bacteria recovery [6,9]. Mechanical filtration is prone to clogging during
61 continuous operation. It also proves challenging with deformable cells such as RBCs,
62 as these can squeeze through membrane pores that are smaller than their size,
63 especially when used in screening of bacteria in blood [6,8].

64 Various label-free microfluidic separation platforms have been developed using
65 acoustic, magnetic, electric, and optical forces [10-12]. In contrast, inertial microfluidics
66 utilizes simple microscale channel geometries and fluid pressure driven flows to
67 accomplish effective and precise control for particle/cell manipulation without
68 additional force fields [13-16]. Some of the broader advantages are its high throughput,
69 predictability, and potential for automation, parallelization and passive continuous
70 separation of particles and cells [17,18]. In addition, several studies have reported cell
71 viability not being significantly affected by the high flow and shear rates often used in
72 inertial microfluidic systems [19-24]. This is presumably because cells are not
73 stationary on a surface, but move and rotate with the fluid without significant
74 deformation [25].

75 Microfluidic channels with different types of straight and curving geometries have been
76 employed for inertial particle and cell focusing, including stepped/expanding channels
77 [8,26-28], spirals [19-21,29-44], single curves [45-48], symmetric and asymmetric
78 serpentine curves [22-24,49-56] and combinations of spiral with asymmetric
79 serpentine curves [57]. Although spiral devices are the most common type of curved
80 geometry employed, a major drawback from spiral and single curved channels that
81 only turn in one direction is the difficulty of arranging many of them in parallel on a

82 single substrate [58]. Serpentine curved channels with alternating directions are more
83 easily parallelized, require less linear distance than straight ones, and by introducing
84 asymmetry in the curvature can achieve similar focusing to spirals [25]. Different
85 designs of serpentine devices have been used for focusing different microparticle
86 sizes (2-20 μm) [23,54], separating multiple blood components [23,53,56,59],
87 pathogenic microorganisms from blood [5,8,60-63], various types of rare cancer cells
88 [51,55,64-66], neurons [24] and pre-concentrating cyanobacteria [49].

89 In this communication, we investigated for the first time curved serpentine channels
90 etched in glass for inertial focusing of small particles and cells (1-10 μm). Two
91 distinctive focusing behaviors from the two etched depths were explored for their
92 potential uses for (i) pathogen pre-concentration, and (ii) separation of pathogenic
93 bacteria from blood.

94 **2 Theory**

95 In microfluidic fluid flow, the relative ratio between inertial and viscous effects in a
96 channel is represented by the dimensionless channel Reynolds number (Re_c) [67]:

$$97 \quad Re_c = \frac{\rho U D_h}{\mu} \quad (1)$$

98 where ρ is the density of the fluid (kg m^{-3}), U is the average flow velocity of the flowing
99 liquid (m s^{-1}), D_h is the hydraulic diameter of the channel (m) calculated as $D_h =$
100 $2wd/(w+d)$ for a rectangular cross-section (w and d being the width and depth of the
101 channel) and μ is the fluid viscosity (Ns m^{-2}). Inertial microfluidics works in an
102 intermediate range ($\sim 1 < Re_c < \sim 100$) between Stokes regime ($Re_c \rightarrow 0$) and turbulent
103 regime ($Re_c \sim 2000$) [15].

104 Taking into account the particle diameter a (m), the particle Reynolds number (Re_p)
105 can be defined to describe the flow of particles in closed channel systems [22,68]:

$$106 \quad Re_p = \frac{\rho U a^2}{\mu D_h} \quad (2)$$

107 Particles suspended in fluids are subjected to hydrodynamic drag and lift forces that
108 are strongly influenced by the fluid dynamic parameters of the system [25,69]. In
109 serpentine channels, two main forces take place: (1) inertial lift and (2) drag forces.
110 Inertial lift forces can be subdivided into the shear gradient lift force (pushing particles

111 away from the channel centerline) and the wall-effect lift force (pushing the particles
 112 away from the channel wall towards the center). The interaction between these two
 113 forces is the net lift force (F_L), which directs the particle towards a stable equilibrium
 114 position within the cross section of the microchannel (Figure 1A). This phenomenon is
 115 known as ‘inertial particle migration’. The net lift force can be expressed as [70]:

$$116 \quad F_L = \frac{\rho U^2 a^4}{D_h^2} f_c \quad (1)$$

117 where f_c is a lift coefficient. This equation illustrates specifically the very strong
 118 dependence of lift force on particle diameter, to the fourth order. Because of this
 119 dependence on a , focusing smaller particles in a given geometry requires much higher
 120 flow velocity (U) and a reduced microchannel cross-sectional area (D_h) than for larger
 121 particles or cells.

122 In a straight channel with square cross-section, particles migrate towards the midpoint
 123 of one of the edges of the wall, generating four equilibrium positions. In a straight
 124 channel with rectangular cross-section, the equilibrium positions reduce to two,
 125 focusing near the midpoints on the wider faces of the channels (Figure 1B) [68,71,72].

126 Drag forces are produced by a secondary flow (Dean flow), which arises when
 127 microscale channels curve or become asymmetric [15,23,68]. Particles in the center
 128 move outwards and circulate back around the channel edges creating two symmetric
 129 and counterrotating vortices perpendicular to the primary flow direction (Figure 1C).
 130 The drag force (F_D) scales as $F_D \sim \rho U^2 a D_h^2 / r$, where r is the radius of curvature of the
 131 channel. Two dimensionless numbers that characterize this secondary flow are the
 132 curvature ratio ($D_h/2r$) and Dean number ($De = Re_c \sqrt{\delta}$), based on the flow velocity in
 133 the channel [25].

134 The competition between the net inertial lift and drag force can be used to manipulate
 135 the focusing profile of particles and reduce the number of equilibrium positions. The
 136 ratio between inertial lift and drag forces is the inertial force ratio (R_f) [25]:

$$137 \quad R_f = \frac{a^2 R}{H^3} \quad (5)$$

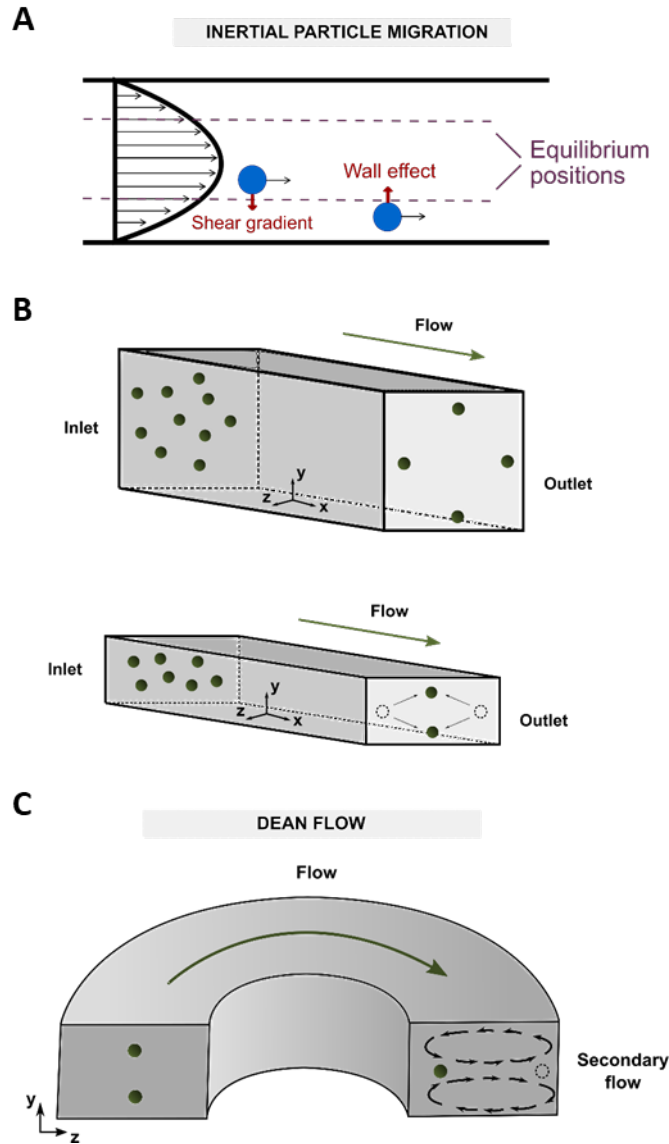
138 where R is the largest radius of curvature (m) in the system and H is the smallest
 139 dimension of the channel (m). To observe focusing, Di Carlo reported $R_f > 0.04$. For a
 140 large R_f value, the inertial lift force dominates the Dean drag force, whilst for a small

141 R_f value the secondary flow effect is dominant. R_f is a strong function of the particle
142 size; as a result, when two different particles are introduced, they can be separated
143 based on their different equilibrium positions.

144 In addition, the ratio of inertial-lift force and the Dean-drag force (F_L/F_D) was expressed
145 as a dimensionless number (δ), taking into account the relationships of the channel
146 curvature ratio ($D_h/2r$), channel aspect ratio (d/w), particle-blockage ratio (a/D_h), and
147 Dean number (De) [13,73]:

$$148 \quad \delta = \frac{a/D_h}{De^{1/2}(D_h/2r)^{3/4}} \quad (6)$$

149 Exploiting δ and a modified particle-blockage ratio, $2(a/D_h)/(1 + d/w)$, reflecting the
150 influence of the channel aspect ratio, a recent experimental operational map was
151 constructed to predict the focusing pattern of different microparticles (5-20 μm) in
152 symmetric sinusoidal microchannels [73].



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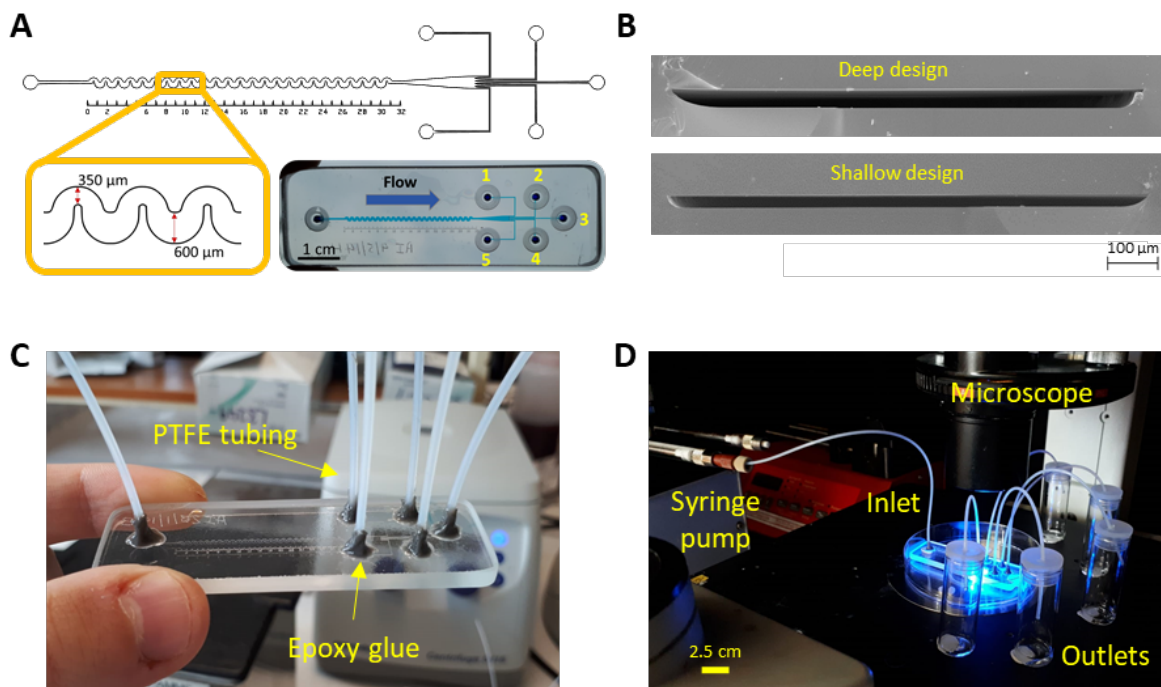
154 **Figure 1.** A) Schematic representation of both inertial lift forces perpendicular to the flow
 155 direction and responsible for the lateral migration of particles to their equilibrium positions in
 156 straight channel flows: (1) Shear-gradient lift force, directed down the shear gradient and (2)
 157 wall-effect lift force, directed away from the wall. B) In square straight channels, particles focus
 158 to four equilibrium regions centred at the faces of the channels. In rectangular straight
 159 channels, particles migrate towards the two wider faces. C) When introducing channel
 160 curvature, a secondary flow (Dean flow) creates two counter-rotating vortices (black arrows)
 161 perpendicular to the primary flow direction.

162 3 Materials and methods

163 3.1 Device design, fabrication, and interfacing

164 Inertial microfluidic devices were designed in AutoCAD (Figure S1, Supporting
 165 Information). Glass devices were patterned onto a 1.15 mm thick glass wafer coated
 166 with chromium and photoresist layers (Schott B270, Tellic, USA) using contact mask

167 lithography. After photo-development and chrome etching, the glass was wet etched
168 with a solution of hydrofluoric acid to a depth of 25 μm or 40 μm (Figure 2A, B) [74].
169 Access holes were CNC drilled (Datron M7) into the etched plate, which was
170 subsequently thermally-bonded to a Schott B270 glass cover plate [75]. The device
171 footprint was 7.5 cm x 2.5 cm. Polytetrafluoroethylene (PTFE) Teflon tubing (1.58 mm
172 OD x 0.5 mm ID, Supelco) was glued (Epoxy Adhesive 2014-2, Araldite) to the inlets
173 and outlets of the device (Figure 2C) and interfaced (adapters and connectors,
174 Kinesis) to a 2.5 mL glass syringe with fixed Luer lock (SGE). Particle/cell suspensions
175 were introduced into the device using a syringe pump (Pump 11 Elite, Harvard
176 Apparatus) (Figure 2D).



177

178 **Figure 2.** A) Device drawing in AutoCAD with channel width dimensions and photograph of
179 final device filled with blue food dye solution. Solutions were pumped from the inlet (left) to the
180 outlets (right). Outlets are numbered as a reference. B) SEM images of the channel cross-
181 section of the two designs: deep design = 40 μm , shallow design = 25 μm . C) Glass inertial
182 microfluidic device interfaced with tubing. D) Typical setup with a syringe pump, glass syringe,
183 device on an inverted microscope and glass vials to collect the outlet effluents.

184 3.2 Particle and cell preparation

185 Suspensions of 10 μm and 4.5 μm yellow-green carboxylate fluorescent particles (λ
186 excitation/emission 441/486 nm) and 1 μm polychromatic red fluorescent particles (λ
187 excitation/emission 525/565 nm) (Fluoresbrite, Polysciences Inc) were prepared in
188 phosphate buffered saline (PBS) and stabilized by adding 0.1% w/v Tween 20 (PBST).
189 Defibrinated horse blood (TCS Biosciences) was prepared by appropriately diluting in

190 PBS. *Escherichia coli* O157:H7 (ATCC® 700728™) was grown in buffered peptone
191 water overnight at 37 °C and serially diluted to the desired concentration in PBST
192 (0.1% w/v). Initial concentration was calculated by UV/vis absorbance at 600 nm
193 (Biochrom Libra S11/S12 UV/vis Spectrophotometer) and plating in sorbitol
194 MacConkey and nutrient agar plates. *E. coli* suspensions from each outlet were
195 quantified by serially diluting and plating on sorbitol MacConkey and nutrient agars.
196 Streams of fluorescent particles and red blood cells (RBCs) flowing through the
197 channels of the microfluidic device were visualized using either a Nikon Eclipse
198 TE2000-U with a Retiga-EXL CCD camera from Media Cybernetics or a Nikon Eclipse
199 Ti inverted microscope. Microparticles and RBCs were counted with a
200 haemocytometer (Improved Neubauer, depth 0.1 mm 1/400 mm², Hawksley).
201 Separation efficiencies for each device and particle/cell size were calculated by
202 dividing the number of particles/cells at each outlet by the sum of the particles/cells of
203 every outlet and multiplying by 100 to give a percentage. Error bars are ± 1 SD of three
204 repeats.

205 For focusing profiles, concentrations of 10⁵ particles mL⁻¹ were used for 10 µm and
206 4.5 µm particles; 10⁷ particles mL⁻¹ for 1 µm particles; 5×10⁶ - 1×10⁷ CFUs mL⁻¹ for *E.*
207 *coli* suspensions; and 1:10 v/v dilution for horse blood. Particles and cells were
208 separately pumped through both devices at volumetric flow rate of 0.7 mL min⁻¹.

209 For separation applications, concentrations of 10⁶ particles mL⁻¹ were used for 10 µm
210 particles; 10⁷ particles mL⁻¹ for 4.5 µm particles; 5×10⁴ CFU mL⁻¹ for *E. coli*; and 1:10,
211 1:30 and 1:50 dilutions for horse blood. Mixtures of particles and *E. coli*, and diluted
212 blood spiked with *E. coli* were pumped only through the deep device at volumetric flow
213 rate of 0.7 mL min⁻¹.

214 **4 Results and discussion**

215 **4.1 Characteristics of serpentine glass devices**

216 The glass devices in this communication were isotropically etched, resulting in
217 'D-shaped' cross-section microchannels (Figure S2, Supporting Information), unlike
218 the majority of inertial focusing devices with rectangular/squared shapes fabricated
219 from PDMS [23,51,53-56,76] or thermoset polyester [49]. Two designs were
220 employed, etched at two different depths from the same photomask, and referred to

221 as ‘shallow design’ (25- μm depth) and ‘deep design’ (40- μm depth). The channel
222 pathway for both devices was laid out asymmetrically, with a series of 49 alternating
223 narrow and wide turns over a distance of 30 mm (Figure 2A). The difference in the
224 radii of curvature between the narrow and wide turns are not as extreme as in
225 asymmetric serpentine devices reported by Di Carlo *et al.* [22,23] (Figure S1, Table
226 S1, Supporting Information). The aspect ratios of our devices are low ($d/w = 0.05$ and
227 0.08 for the shallow and deep designs, respectively) compared to other reported
228 serpentine channels (≥ 0.1) [23,49,51]. Due to the ‘D-shaped’ cross-section of our
229 devices, the two counter-rotating vortices in the upper and lower parts of the channel
230 are not symmetrical as in rectangular channels. However, the asymmetry of these
231 vortices are presumably minute in such low aspect ratio channels ($w \gg d$). De are
232 17.5 and 15.3 for the deep and shallow devices, respectively, similar to $De = 21.1$
233 reported in other asymmetric serpentine devices [22,23].

234 **4.2 Focusing profiles of microparticles**

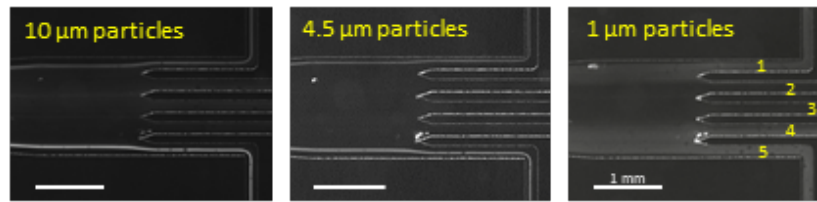
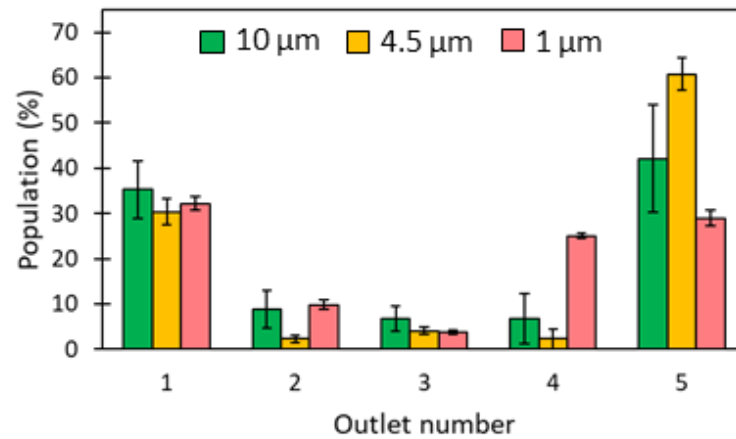
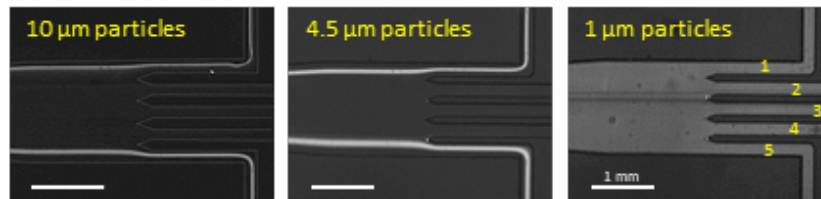
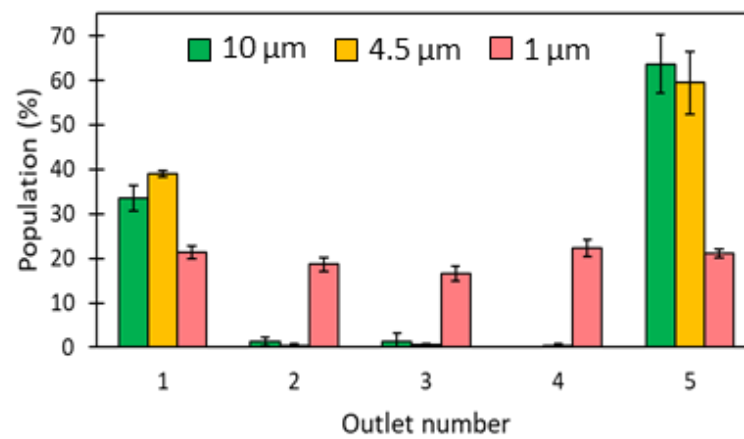
235 The deep design was first assessed with rigid polystyrene particles ($10 \mu\text{m}$ and 4.5
236 μm) at volumetric flow rates of $0.5 - 1 \text{ mL min}^{-1}$ ($Re_c = 37 - 74$, Figure S3-A,B,
237 Supporting Information). Focusing was observed along the channel edges, similarly to
238 inertial focusing typically reported in symmetric serpentine channels where inertial lift
239 forces dominate [22,51,56]. Reducing equilibrium positions from two to a single stream
240 at the channel center with $\geq 8 \mu\text{m}$ -particles was reported in a symmetric serpentine
241 device with increasing flow rates ($Re_c \geq 87$) [51]. In addition, according to the
242 experimental operational map recently reported by the same group [73], $10 \mu\text{m}$
243 particles in our deep device should experience one-position focusing at $Re_c \geq 74$.
244 However, no such transition was observed in our device ($74 \leq Re_c \leq 147$, results not
245 shown here), presumably due to 3x smaller aspect ratio (d/w) of our device compared
246 with Zhang’s.

247 Above 0.7 mL min^{-1} , the mixing effect became predominant again with increasing flow
248 velocities, resulting in a small migration of $4.5 \mu\text{m}$ particles into exit 4 (Figure S3-B,
249 Supporting Information). Therefore, a fixed flow rate of 0.7 mL min^{-1} was chosen for
250 further investigations on focusing profiles of different particles.

251 Suspensions of fluorescent microparticles of different sizes (10 , 4.5 and $1 \mu\text{m}$) were
252 separately pumped through both designs at a volumetric flow rate of 0.7 mL min^{-1} (U
253 $= 91 \text{ cm s}^{-1}$, $Re_c = 56$, for the shallow design; and $U = 54 \text{ cm s}^{-1}$, $Re_c = 51$, for the deep

254 design). Particle trajectories were monitored and visualized using an inverted
255 fluorescent microscope (Figure 3). Particles of 10 μm and 4.5 μm migrated to the
256 channel edges in both devices, exiting through outlets 1 and 5, following Zhang's
257 experimental operational map [73] (Table S3, Supporting Information). Small particles
258 of 1 μm focused to some extent within the shallow design, collecting 61% through
259 outlets 1 and 5 (Figure 3A). In contrast, 1 μm beads did not experience enough inertial
260 lift force in the migration process even with the Dean flow assistance, and therefore
261 remained unfocused in the deep design ($\sim 20\%$ in each outlet, Figure 3B).

262 As demonstrated in Equation 1, the net lift force (F_L) depends very strongly on particle
263 diameter, to the fourth order. This translates that at the same flow velocity and channel
264 dimensions, smaller particles, in this case 1 μm , will focus to a lesser extent or not
265 focus at all. Another relevant parameter is the inertial force ratio (R_f), introduced in
266 Equation 5. Di Carlo [22] reported values of $R_f > 0.04$ to observe particle focusing. In
267 our case, the R_f values for focused 10 μm and 4.5 μm particles in both devices into
268 two streams along the channel side walls are > 0.04 . Random migration of 1 μm
269 particles was observed in the deep device ($R_f = 0.01$). In contrast, partial focusing of
270 1 μm particles was observed in the shallow device, where $R_f = 0.04$, closer to the cut-
271 off value. With further reduction in channel depth, a complete focus of 1 μm particles
272 might theoretically be possible.

A**Shallow design****B****Deep design**

273

274 **Figure 3.** Fluorescent microscope photographs and focusing profiles of microparticles of
 275 different sizes (10, 4.5 and 1 μm) in (A) shallow (25 μm) channel design, and (B) deep (40
 276 μm) channel design. Particle suspensions were separately pumped at 0.7 mL min⁻¹ (n = 3).

277

278 4.3 Focusing profiles of cells

279 The deep design was tested with *E. coli* O157 cells (1-2 μm long, 0.5 μm wide [77]) at
280 flow rates of 0.5 – 1 mL min^{-1} . In contrast to the larger 10 μm and 4.5 μm particles, *E.*
281 *coli* remained unfocused (Figure S3-C, Supporting Information and Figure 4B). Due to
282 the much smaller size of *E. coli* cells, they are more affected by the counter-rotating
283 streamlines of a Dean vortex, and hence it is more difficult to align into equilibrium
284 positions [50,51].

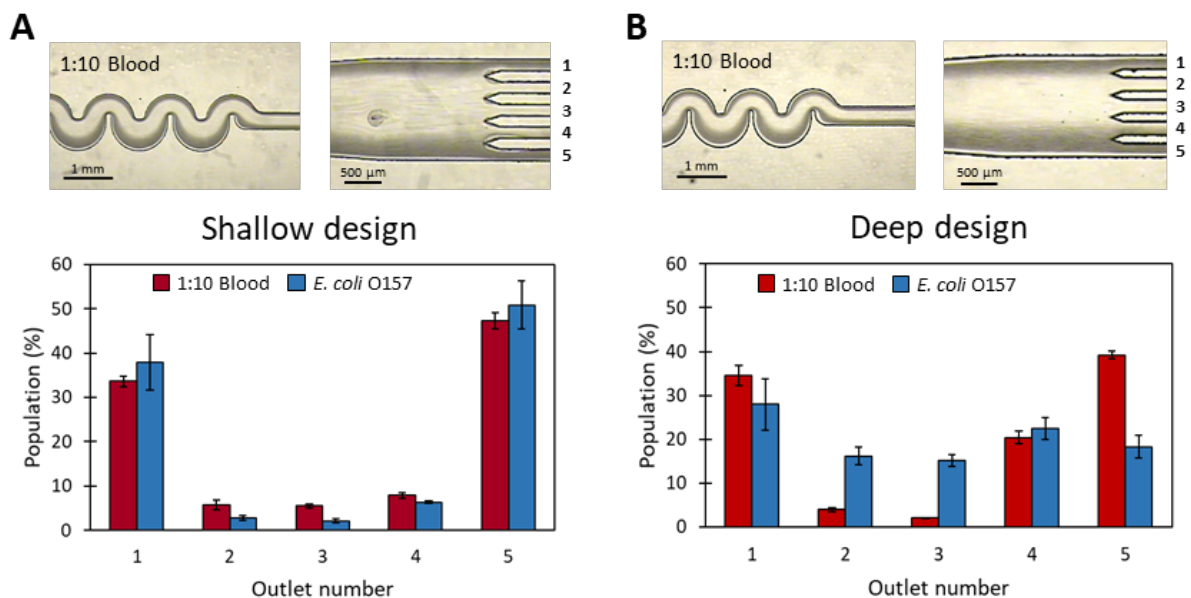
285 The focusing profile of *E. coli* in the shallow device differed from the deep design. The
286 bacterial cells focused along the channel edges and exited at outlets 1 and 5 (recovery
287 of ca. 89% at 0.7 mL min^{-1} , Figure S3-D, Supporting Information and Figure 4A).
288 Interestingly, this shows that at the same $Re_c = 56$, the equilibrium positions of
289 particles/cells ranging 10 – 1.5 μm were preferential along the channel side walls of
290 the shallow device. With increasing flow velocities, the mixing effect became
291 predominant, and a small migration of cells into exit 4 was observed (Figure S3-C,
292 Supporting Information).

293 The difference between the *E. coli* focusing behaviors in the two designs (deep design:
294 non-focused, and shallow design: focused) can be attributed to the suppression of the
295 mixing effect of Dean vortex with lower channel depth [50,51]. Additionally, R_f values
296 of *E. coli* (calculated using 1.5 μm diameter) were 0.09 and 0.02 for the shallow and
297 deep designs, respectively ($R_f > 0.04$ to observe focusing [25]).

298 The two device designs were also subjected to 1:10 diluted horse blood cells (Figure
299 4). The RBCs are 6-8 μm in diameter [78], and should theoretically behave similarly to
300 the 10 μm particles. Indeed, focusing of RBCs was observed along the channel edges
301 and exited through outlets 1 and 5 in both devices. The performance of the shallow
302 design was superior (89% recovery from outlets 1 and 5), whereas migration of RBCs
303 into outlet 4 (20%) was seen in the deep device. Due to similar focusing behaviors of
304 *E. coli* and RBCs in the shallow device (Figure 4A), it will not be possible to employ
305 this design for separation of *E. coli* from blood matrix. However, the shallow design
306 displayed a pre-concentration factor of x2.2 for *E. coli* cells, which could be useful to
307 pre-enrich such bacteria, and those of similar sizes, in samples where narrow size-
308 based separation (1-10 μm) is not needed. This pre-concentration factor could be
309 increased by redesigning the side outlets to collect less volume. In addition,
310 decreasing the channel depth to increase R_f can also be further investigated for

311 improved focusing performance. Such a high-throughput pre-concentration device
 312 could be beneficial in bacteria concentration from urine samples for diagnostics of
 313 urinary tract infections. Wang and Dandy [49] used an asymmetric serpentine device
 314 for pre-concentration of cyanobacteria, which have a similar size ($2\ \mu\text{m}$) to *E. coli*.
 315 However, whilst demonstrating an excellent 98% bacterial recovery with 3.2x pre-
 316 concentration factor, the significantly narrower dimensions of their device ($20\ \mu\text{m}$
 317 narrowest width x $10\ \mu\text{m}$ depth) can be challenging for fabrication. In addition, this
 318 device required a filter to prevent clogging, which would be likely to happen in such a
 319 small cross-section.

320 In the deep device, however, RBCs and *E. coli* followed different focusing profiles.
 321 Whilst RBCs preferentially migrated along the channel edges, *E. coli* behaved similarly
 322 to $1\ \mu\text{m}$ particles and mostly remained unfocused (Figure 4B). Together with previous
 323 microparticle results, the deep device showed the potential for applications requiring
 324 the separation of *E. coli* from larger microparticles and RBCs.



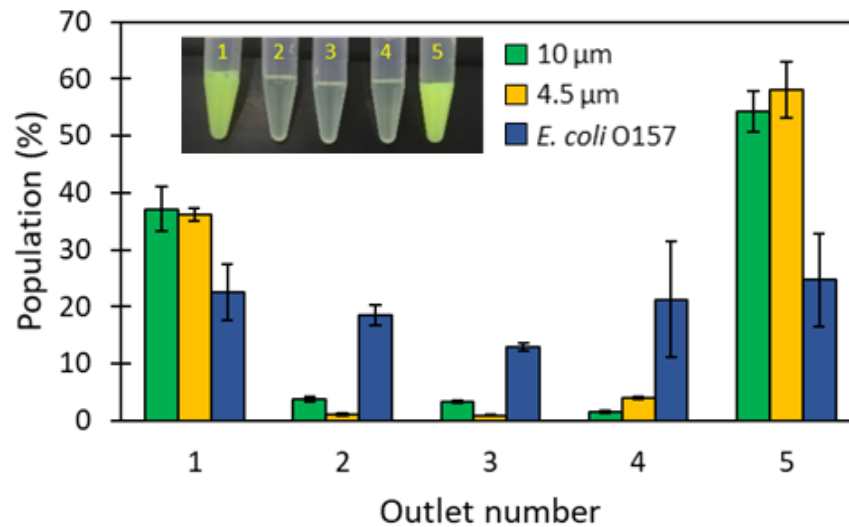
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326 **Figure 4.** Microscope photographs and focusing profiles of 1:10 blood and *E. coli* O157 in (A)
 327 shallow ($25\ \mu\text{m}$) channel design, and (B) deep ($40\ \mu\text{m}$) channel design. Diluted blood and *E.*
 328 *coli* O157 suspensions were separately pumped at $0.7\ \text{mL min}^{-1}$ ($n = 3$).

329 4.4 Separation of microparticles and *E. coli* O157

330 To study the separation performance of the deep design, a suspension of $10\ \mu\text{m}$ and
 331 $4.5\ \mu\text{m}$ fluorescent particles and *E. coli* was pumped through the device. The focusing
 332 behaviour of mixed particles followed the same pattern as when they were separately
 333 introduced. Results reported a successful recovery of 53% *E. coli* (outlets 2-4)

334 depleted from 91% of 10 μm beads and 94% of 4.5 μm beads, which were obtained
335 through outlets 1 and 5 (Figure 5).



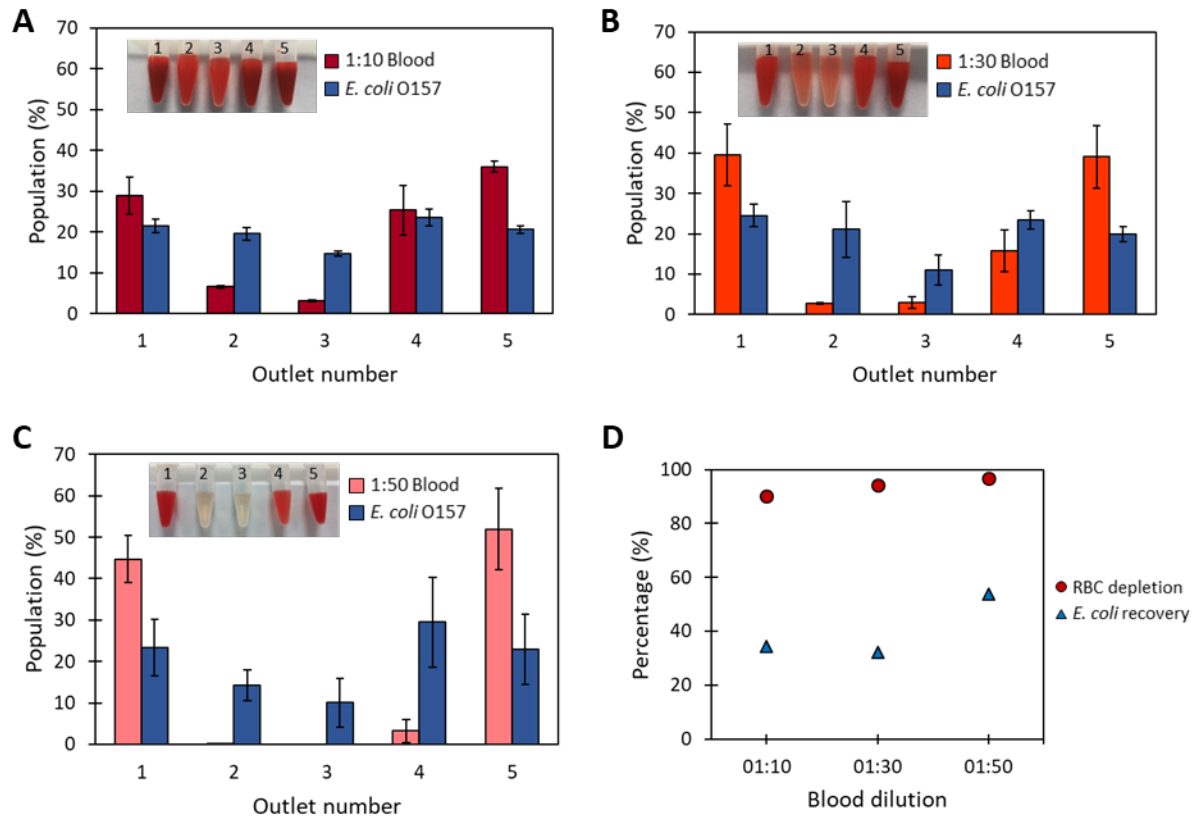
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337 **Figure 5.** Inertial separation of a mixture of 10 μm (10^6 particles mL^{-1}) and 4.5 μm (10^7 particle
338 mL^{-1}) fluorescent particles spiked with *E. coli* O157 (5×10^4 CFU mL^{-1}) on the deep (40 μm)
339 channel design. The mixture was pumped at 0.7 mL min^{-1} ($n = 3$).

340 **4.5 Separation of *E. coli* from blood samples**

341 Although focusing of $\geq 8 \mu\text{m}$ particles in a single stream inside a symmetrical channel
342 was reported [51], inertial blood separation has been performed in devices where
343 focusing of RBCs took place in two streams along the channel edges [8,56]. When
344 high concentrations of particles/cells (*i.e.* blood) flow through a channel, particle/cell
345 ordering in a single narrow stream is more challenging due to steric crowding effects
346 [79]. Instead, symmetric focusing in two streams along the channel side walls can be
347 more easily achieved. Here, we exploited the inertial equilibrium positions of RBCs
348 along the channel edges of the deep design for *E. coli* recovery from blood.

349 In order to reduce the steric effects associated with high blood cell concentration,
350 blood was diluted 10x, 30x and 50x in PBST. Each dilution was spiked with similar *E.*
351 *coli* O157 concentration of 5×10^4 CFU mL^{-1} . With increasing blood dilutions, higher
352 separation of RBCs was obtained, thus improving the device efficiency. Recovery of
353 54% of *E. coli* depleted from 97% RBCs was achieved with a single pass of *E. coli*-
354 spiked 1:50 blood (Figure 6).



355

356 **Figure 6.** Inertial separation of diluted horse blood solutions; (A) 1:10, (B) 1:30 and (C) 1:50
 357 spiked with *E. coli* O157 on the deep (40 μm) channel design. (D) RBC depletion and *E. coli*
 358 recovery from different blood dilutions. The mixtures were pumped at 0.7 mL min^{-1} ($n = 3$).

359 To compare the performance of our device with other inertial devices reported for
 360 separation of bacteria from blood, blood dilutions were calculated as % hematocrit (Hct
 361 = volume percentage of red blood cells in blood). Human blood has an average of 45%
 362 Hct for men and 40% Hct for women [56], whilst Hct from adult horse blood ranges
 363 between 31 to 50% [80].

364 A logical target is to separate a few bacteria from billions of RBCs from blood usually
 365 collected in vacutainer tubes (7-10 mL) in less than 10 min in order to provide time for
 366 downstream processes for molecular identification of pathogenic species [6]. Table 1
 367 summarizes performances of inertial microfluidic devices for separation of bacteria
 368 from blood. The comparisons are based on operation in a single unit. Our device
 369 showed superior performance for RBCs depletion (97%) from less diluted blood
 370 (0.81% Hct) and higher throughput compared to the expanding straight channel device
 371 (88% RBCs depletion from 1:200 blood, 0.21% Hct) [8]. Although fewer *E. coli* cells
 372 were recovered, 54% efficiency was achieved after a single pass through the device.

373 Hou *et al.* [5] developed a spiral device for separating low concentrations of *E. coli*
374 (10-100 CFU mL⁻¹) from blood, employing a sheath fluid with x10 the sample flow.
375 Besides yielding >65% *E. coli* recovery from 1:3 diluted blood (~15% Hct) at 150 μL
376 min⁻¹ flowrate, an array of 14 spiral devices would be required in order to process 7
377 mL of blood in 10 min. Parallelization for throughput improvement can be difficult to
378 achieve within the physical confines of the device compared to serpentine/straight
379 channels, especially when two pumps are required to control two independent inlet
380 flows. Faridi *et al.* [62] combined inertial microfluidics with a non-Newtonian
381 polyethylene oxide (PEO) sheath flow to recover 76% *E. coli* from whole blood with
382 the lowest generated waste volume. However, at such low flow rate of 0.5 μL min⁻¹,
383 an impractically high number of single units would need to be run in parallel to process
384 7 mL of whole blood in a relevant time scale. Wu *et al.* [60] exploited a soft inertial
385 force device to separate *E. coli* mixed into human blood using a flow system in which
386 the diluted blood was sheathed with another flow, and subsequently deflected by an
387 'acting' flow. This system allowed for 300-fold bacteria enrichment (62% recovery)
388 from 1:10 human blood at 18 μL min⁻¹. However, the three-inlet system for the acting
389 flows requires a more complex fluidic control and generates large volumes of fluid to
390 be discarded, making it impractical to process 7 mL of whole blood in 10 min [6]. Using
391 the channel design reported herein, an arrangement of 50 separating channels in
392 parallel, fed from a single inlet, would have a potential maximum throughput of 7 mL
393 of whole blood in 10 min. Such a multiplexing array could be fabricated to sit within a
394 10 cm radius footprint.

395 **Table 1.** Performance of different inertial devices for separation of RBC based on a single unit.

Device	Asymmetric serpentine channel (this work)	Expanding straight channel [8]	Spiral channel [5]	Elasto-inertial straight channel [62]	Soft inertial-based channel [60]
Blood dilution	1:50	1:200	1:3	non-diluted	1:10
Hematocrit (%)	0.81*	0.21**	~15	42.5**	4.25**
RBC depletion (%)	97	88	-	-	98
<i>E. coli</i> recovery (%)	54	>80	>65	76	62
Flow rate ($\mu\text{L min}^{-1}$)	700	200	150	0.5	18
Number of passes	1	2	1	1	1
Time required to process 7 mL of whole blood (h)	8.3	117	2.3	233	65
Total liquid volume needed to process 7 mL of whole blood (mL)	350	1400	231	91	798

396 *Calculated from an average of 40.5% horse hematocrit. **Calculated from an average of 42.5% human hematocrit.

397

398

399 In summary, we have explored, for the first time, glass serpentine devices for inertial
400 focusing of small microparticles (1-10 μm) and cells ($\leq 8 \mu\text{m}$). Two different designs
401 based on etched depth displayed different focusing behaviors and can be used for
402 different applications. The ability of the shallow device to focus 1 μm particles and *E.*
403 *coli* O157 (x2.2 preconcentrating factor) shows promise for bacteria pre-concentration
404 applications. The feasibility of using the deep design for separation of *E. coli* from
405 larger microparticles and RBCs (54% *E. coli* recovered from 97% depleted RBCs in
406 0.81% hematocrit) has been demonstrated. By parallelizing such serpentine channels,
407 separation of bacteria from relevant volumes of 7 mL whole blood could potentially be
408 achieved in 10 minutes. Such a platform would facilitate detection of pathogenic
409 bacteria in blood with no or minimal culturing, thereby allowing faster diagnostics and
410 timely assessment and treatment.

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415 **Conflict of interest**

416 The authors have declared no conflict of interest.

417 **Data Availability Statement**

418 The data that support the findings of this study are available from the corresponding
419 author upon reasonable request.

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549 **Supporting information**

550 **Supporting information file:** Inertial microfluidic devices; Effect of flow rates on
551 inertial focusing of particles and *E. coli* O157; Estimated values of F_L/F_D scaling factor
552 and modified particle-blockage ratio.

Supporting Information

Inertial focusing of microparticles, bacteria and blood in serpentine glass channels

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Table of contents

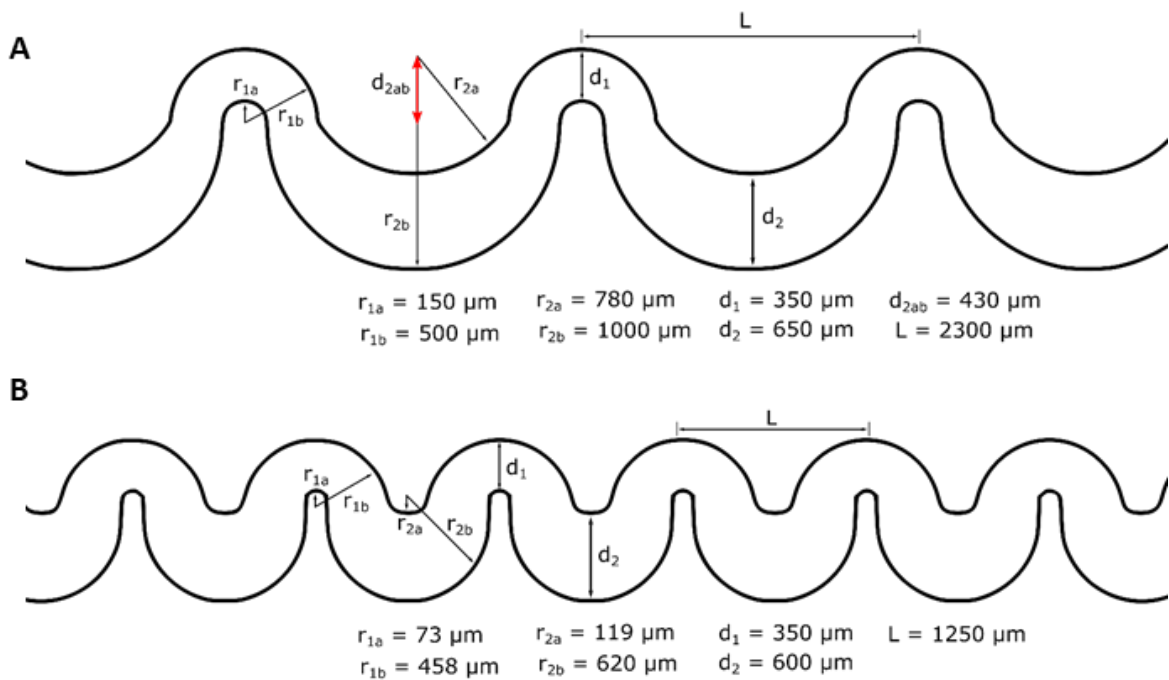
Section S1 - Inertial microfluidic devices

Section S2 - Effect of flow rates on inertial focusing of particles and *E. coli* O157

Section S3 - Estimated values of F_L/F_D scaling factor and modified particle-blockage ratio

23 **S1 Inertial microfluidic devices**

24 Two designs were employed, etched at two different depths from the same
 25 photomask, and referred to as 'shallow design' (25- μm depth) and 'deep design' (40-
 26 μm depth). The channel pathway for both devices was laid out asymmetrically, with a
 27 series of 49 alternating narrow and wide turns over a distance of 30 mm. The radii of
 28 curvature between the narrow and wide turns, $(r_{1b}/r_{1a})/(r_{2b}/r_{2a})$, in our device are more
 29 similar compared to those used in asymmetric serpentine devices reported by Di Carlo
 30 *et al.* [1,2]. This also results in our device having a distance between two narrow turns
 31 (L) almost half as Di Carlo's (Figure S1, Table S1).



32

33 **Figure S1.** Comparison of dimensions and radii of curvature between Di Carlo's
 34 device (A), and ours (B), etched at two depths.

35

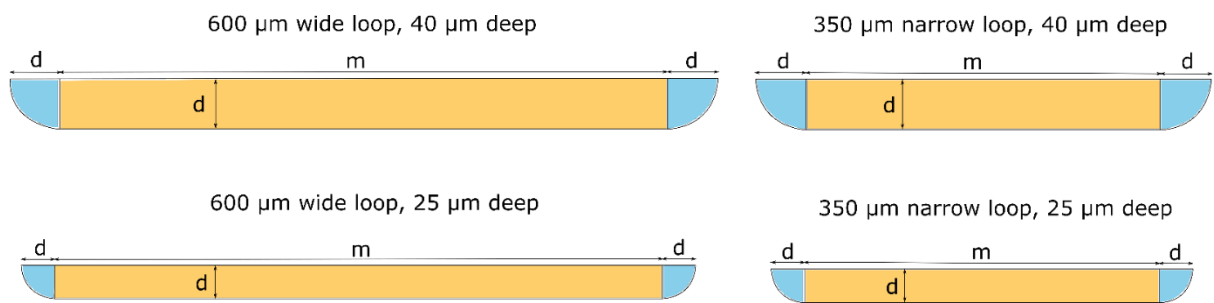
36 **Table S1.** Comparison of radii of curvature and turn ratios between Di Carlo's device
 37 and ours.

	Our device	Di Carlo's [2]
Largest radius in narrow turn, r_{1b} (μm)	458	500
Smallest radius in narrow turn, r_{1a} (μm)	73	150
r_{1b}/r_{1a} (narrow turn)	6.3	3.3
Largest radius in wide turn, r_{2b} (μm)	620	1000
Smallest radius in wide turn, r_{2a} (μm)	119	780
r_{2b}/r_{2a} (wide turn)	5.2	1.3
$(r_{1b}/r_{1a}) / (r_{2b}/r_{2a})$	1.2	2.6
Distance between two narrow turns, L (μm)	1250	2300

38

39 The microfluidic glass channels were etched with dilute hydrofluoric acid using a
 40 photomask of width m . Due to isotropic etching, the final channel width at the bottom
 41 will be the photomask width m , but the final channel width at the top (w) will be wider,
 42 and can be determined according to $w = (2d) + m$, where d is the channel depth. This
 43 means that for a channel etched at $40 \mu\text{m}$ deep, the final top width will be $80 \mu\text{m}$ wider
 44 than the photomask/bottom width ($40 \mu\text{m}$ on each side). This results in curved
 45 sidewalls (Figure S2).

46



47

48 **Figure S2.** Cross-sectional areas of the narrow and wide turns in both shallow and
 49 deep devices after isotropic hydrofluoric acid etching of glass.

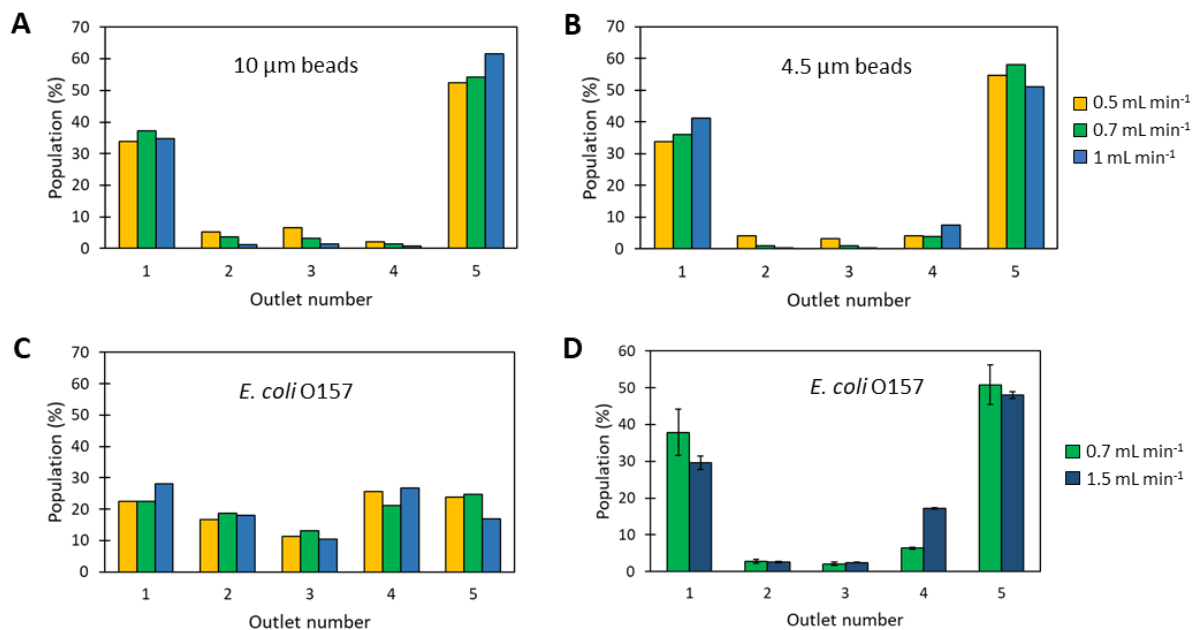
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53 **S2 Effect of flow rates on inertial focusing of particles and *E. coli* O157**

54 Different flow rates were investigated for focusing of particles and *E. coli* O157. For
55 the deep design, increasing flowrate resulted in better depletion of 10 μm particles,
56 but worsened the focusing for 4.5 μm particles (Figure S3 A, B). Flow rate had no
57 significant effect on the focussing of the *E. coli* in the deep design (Figure S3 C). For
58 the shallow device, 0.7 mL min^{-1} flow rate resulted in better focusing of *E. coli* (Figure
59 S3 D).



60

61 **Figure S3.** Focusing profiles of (A) 10 μm , (B) 4.5 μm and (C) *E. coli* at 0.5, 0.7 and 1
62 mL min^{-1} on the deep design. (D) Focusing profiles of *E. coli* at 0.7 and 1.5 mL min^{-1}
63 on the shallow design.

64 **S3 Estimated values of F_L/F_D scaling factor and modified particle-blockage ratio**

65 **Table S2.** Comparison of F_L/F_D scaling factor (δ) and modified particle-blockage ratio
66 (MPBR) [3] of different particle sizes in both devices operating at 0.7 mL min⁻¹.

Particle size (μm)	Deep device ($Re_c = 56$)			Shallow device ($Re_c = 52$)		
	10	8*	4.5	10	8*	4.5
δ	0.10	0.08	0.04	0.22	0.18	0.10
MPBR	0.19	0.16	0.09	0.31	0.25	0.14

67 *Approximated particle size of red blood cells.

68

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